

Resource theory of contextual behaviours



Samson Abramsky¹



Rui Soares Barbosa¹



Shane Mansfield²



Martti Karvonen³



Workshop on Contextuality as a Resource in Quantum Computation
Oxford, 4th July 2019

Motivation

- ▶ Central object of study of quantum information and computation theory: the **advantage** afforded by **quantum resources** in information-processing tasks.

Motivation

- ▶ Central object of study of quantum information and computation theory: the **advantage** afforded by **quantum resources** in information-processing tasks.
- ▶ A range of examples are known and have been studied . . . but a systematic understanding of the scope and structure of quantum advantage is lacking.

Motivation

- ▶ Central object of study of quantum information and computation theory: the **advantage** afforded by **quantum resources** in information-processing tasks.
- ▶ A range of examples are known and have been studied . . . but a systematic understanding of the scope and structure of quantum advantage is lacking.
- ▶ A hypothesis: this is related to **non-classical** features of quantum mechanics.

Motivation

- ▶ Central object of study of quantum information and computation theory: the **advantage** afforded by **quantum resources** in information-processing tasks.
- ▶ A range of examples are known and have been studied . . . but a systematic understanding of the scope and structure of quantum advantage is lacking.
- ▶ A hypothesis: this is related to **non-classical** features of quantum mechanics.
- ▶ In this talk, we focus on **non-local** and **contextual** behaviours as quantum resources.
- ▶ Contextuality is a feature of **empirical data** that is a key signature of non-classicality.

Overview

Overview

- ▶ Unified, theory-independent framework for non-locality and contextuality
 - '*The sheaf-theoretic structure of non-locality and contextuality*'
Abramsky, Brandenburger, New Journal of Physics, 2011.
 - (cf. Cabello–Severini–Winter, Acín–Fritz–Leverrier–Sainz)

Overview

- ▶ Unified, theory-independent framework for non-locality and contextuality

'The sheaf-theoretic structure of non-locality and contextuality'

Abramsky, Brandenburger, New Journal of Physics, 2011.

(cf. Cabello–Severini–Winter, Acín–Fritz–Leverrier–Sainz)

- ▶ A resource theory for contextuality:

- ▶ Measure of contextuality

- ▶ Combine and transform contextual blackboxes

- ▶ Quantifiable advantages in QC and QIP tasks

'Contextual fraction as a measure of contextuality'

Abramsky, B, Mansfield, Physical Review Letters, 2017.

'A comonadic view of simulation and quantum resources'

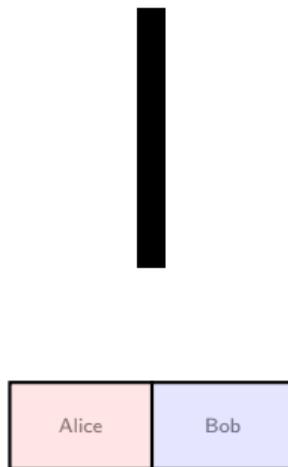
Abramsky, B, Karvonen, Mansfield, LiCS 2019.

Contextuality

Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

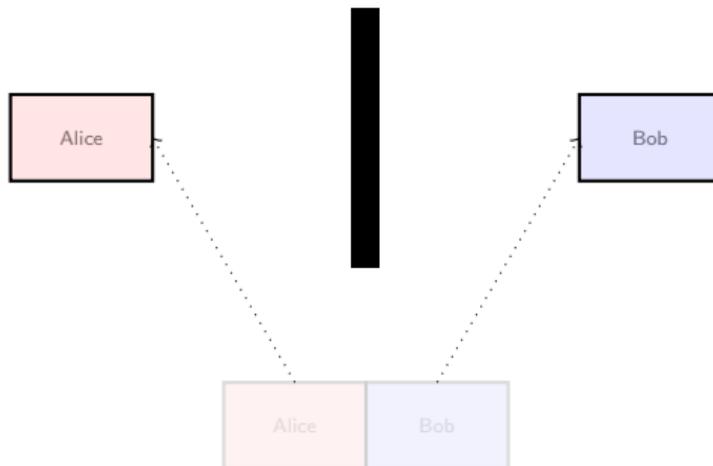
They may share prior information,



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

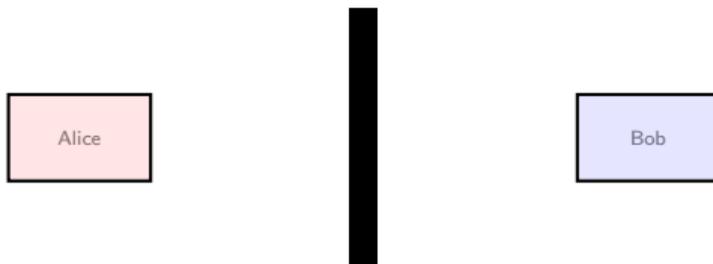
They may share prior information,



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

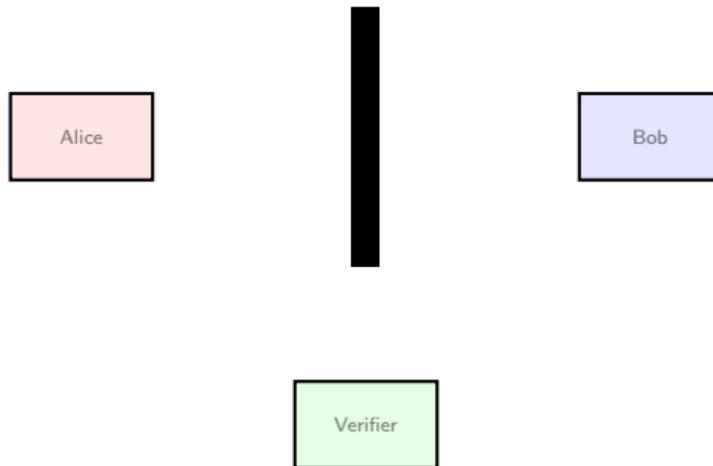
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

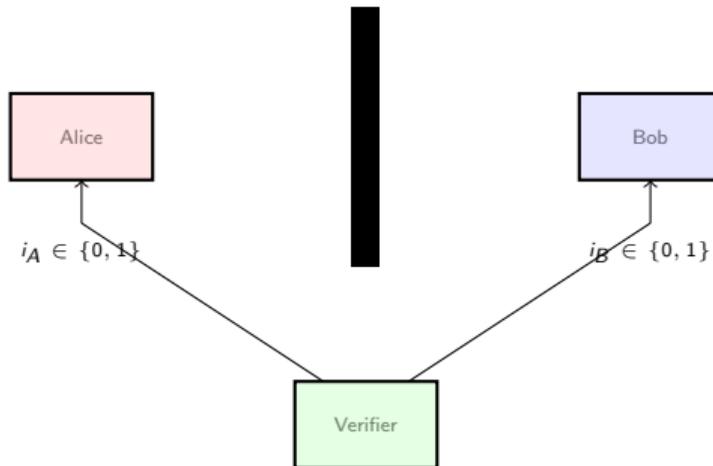
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

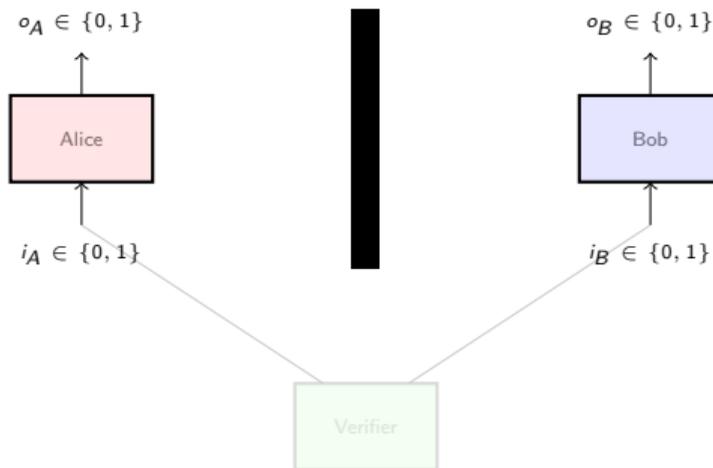
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

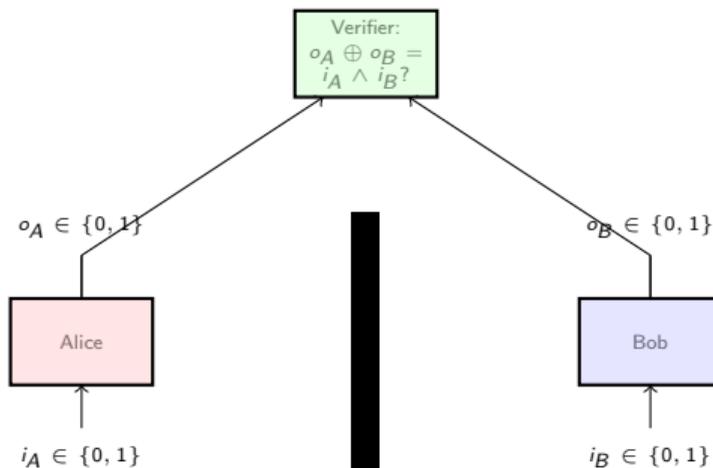
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

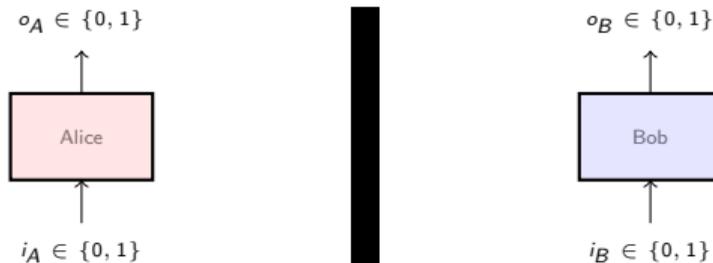
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

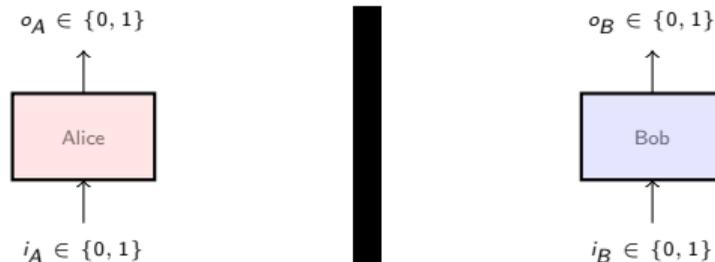
They may share prior information, but cannot communicate once the game starts.



Non-local games

Alice and Bob cooperate in solving a task set by Verifier.

They may share prior information, but cannot communicate once the game starts.



They win a play if $o_A \oplus o_B = i_A \wedge i_B$.

A strategy is described by the probabilities $P(o_A, o_B \mid i_A, i_B)$.

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	$1/2$	0	0	$1/2$
0	1	$3/8$	$1/8$	$1/8$	$3/8$
1	0	$3/8$	$1/8$	$1/8$	$3/8$
1	1	$1/8$	$3/8$	$3/8$	$1/8$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

This gives a winning probability of $3.25/4 \approx 0.81$!

Non-local games

- ▶ Sharing a pair of qubits and performing quantum measurements, Alice and Bob can realise:

A	B	(0,0)	(0,1)	(1,0)	(1,1)
0	0	1/2	0	0	1/2
0	1	3/8	1/8	1/8	3/8
1	0	3/8	1/8	1/8	3/8
1	1	1/8	3/8	3/8	1/8

Assuming a uniform distribution on inputs,

$$\begin{aligned} P(o_A \oplus o_B = i_A \wedge i_B) &= \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 0) + \frac{1}{4} P(o_A = o_B \mid i_A = 0, i_B = 1) \\ &\quad + \frac{1}{4} P(o_A = o_B \mid i_A = 1, i_B = 0) + \frac{1}{4} P(o_A \neq o_B \mid i_A = 1, i_B = 1) \end{aligned}$$

This gives a winning probability of $3.25/4 \approx 0.81$!

- ▶ Classically, Alice and Bob's optimal winning probability is 0.75.

A simple observation

'*Logical Bell inequalities*', Abramsky, Hardy, Physical Review A, 2012.

A simple observation

'*Logical Bell inequalities*', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N

A simple observation

'*Logical Bell inequalities*', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$

A simple observation

'*Logical Bell inequalities*', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}\left(\neg \bigwedge \phi_i\right)$$

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}(\neg \bigwedge \phi_i) = \text{Prob}(\bigvee \neg \phi_i)$$

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}(\neg \bigwedge \phi_i) = \text{Prob}(\bigvee \neg \phi_i) \leq \sum_{i=1}^N \text{Prob}(\neg \phi_i)$$

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}(\neg \bigwedge \phi_i) = \text{Prob}(\bigvee \neg \phi_i) \leq \sum_{i=1}^N \text{Prob}(\neg \phi_i) = \sum_{i=1}^N (1 - p_i)$$

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}(\neg \bigwedge \phi_i) = \text{Prob}(\bigvee \neg \phi_i) \leq \sum_{i=1}^N \text{Prob}(\neg \phi_i) = \sum_{i=1}^N (1 - p_i) = N - \sum_{i=1}^N p_i .$$

A simple observation

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ Propositional formulae ϕ_1, \dots, ϕ_N
- ▶ $p_i := \text{Prob}(\phi_i)$
- ▶ Suppose the ϕ_i are not simultaneously satisfiable. Then $\text{Prob}(\bigwedge \phi_i) = 0$.
- ▶ Using elementary logic and probability:

$$1 = \text{Prob}(\neg \bigwedge \phi_i) = \text{Prob}(\bigvee \neg \phi_i) \leq \sum_{i=1}^N \text{Prob}(\neg \phi_i) = \sum_{i=1}^N (1 - p_i) = N - \sum_{i=1}^N p_i .$$

- ▶ Hence,

$$\sum_{i=1}^N p_i \leq N - 1 .$$

Analysis of the Bell table

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	$1/2$	0	0	$1/2$
a_0	b_1	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_0	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_1	$1/8$	$3/8$	$3/8$	$1/8$

Analysis of the Bell table

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	$1/2$	0	0	$1/2$
a_0	b_1	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_0	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_1	$1/8$	$3/8$	$3/8$	$1/8$

$$\begin{aligned}\phi_1 &= a_0 \leftrightarrow b_0 = (a_0 \wedge b_0) \vee (\neg a_0 \wedge \neg b_0) \\ \phi_2 &= a_0 \leftrightarrow b_1 = (a_0 \wedge b_1) \vee (\neg a_0 \wedge \neg b_1) \\ \phi_3 &= a_1 \leftrightarrow b_0 = (a_1 \wedge b_0) \vee (\neg a_1 \wedge \neg b_0) \\ \phi_4 &= a_1 \oplus b_1 = (\neg a_1 \wedge b_1) \vee (a_1 \wedge \neg b_1).\end{aligned}$$

Analysis of the Bell table

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	$1/2$	0	0	$1/2$
a_0	b_1	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_0	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_1	$1/8$	$3/8$	$3/8$	$1/8$

$$\begin{aligned}\phi_1 &= a_0 \leftrightarrow b_0 = (a_0 \wedge b_0) \vee (\neg a_0 \wedge \neg b_0) \\ \phi_2 &= a_0 \leftrightarrow b_1 = (a_0 \wedge b_1) \vee (\neg a_0 \wedge \neg b_1) \\ \phi_3 &= a_1 \leftrightarrow b_0 = (a_1 \wedge b_0) \vee (\neg a_1 \wedge \neg b_0) \\ \phi_4 &= a_1 \oplus b_1 = (\neg a_1 \wedge b_1) \vee (a_1 \wedge \neg b_1).\end{aligned}$$

These formulae are contradictory.

Analysis of the Bell table

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	$1/2$	0	0	$1/2$
a_0	b_1	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_0	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_1	$1/8$	$3/8$	$3/8$	$1/8$

$$\begin{aligned}\phi_1 &= a_0 \leftrightarrow b_0 = (a_0 \wedge b_0) \vee (\neg a_0 \wedge \neg b_0) \\ \phi_2 &= a_0 \leftrightarrow b_1 = (a_0 \wedge b_1) \vee (\neg a_0 \wedge \neg b_1) \\ \phi_3 &= a_1 \leftrightarrow b_0 = (a_1 \wedge b_0) \vee (\neg a_1 \wedge \neg b_0) \\ \phi_4 &= a_1 \oplus b_1 = (\neg a_1 \wedge b_1) \vee (a_1 \wedge \neg b_1).\end{aligned}$$

These formulae are contradictory. But $p_1 + p_2 + p_3 + p_4 = 3.25$. The inequality is violated by $1/4$.

Analysis of the Bell table

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	$1/2$	0	0	$1/2$
a_0	b_1	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_0	$3/8$	$1/8$	$1/8$	$3/8$
a_1	b_1	$1/8$	$3/8$	$3/8$	$1/8$

$$\begin{aligned}\phi_1 &= a_0 \leftrightarrow b_0 = (a_0 \wedge b_0) \vee (\neg a_0 \wedge \neg b_0) \\ \phi_2 &= a_0 \leftrightarrow b_1 = (a_0 \wedge b_1) \vee (\neg a_0 \wedge \neg b_1) \\ \phi_3 &= a_1 \leftrightarrow b_0 = (a_1 \wedge b_0) \vee (\neg a_1 \wedge \neg b_0) \\ \phi_4 &= a_1 \oplus b_1 = (\neg a_1 \wedge b_1) \vee (a_1 \wedge \neg b_1).\end{aligned}$$

These formulae are contradictory. But $p_1 + p_2 + p_3 + p_4 = 3.25$. The inequality is violated by $1/4$.

All Bell inequalities arise in this way.

Contextuality

- ▶ The Bell table can be realised in the real world.

Contextuality

- ▶ The Bell table can be realised in the real world.
- ▶ So, what was our unwarranted assumption?

Contextuality

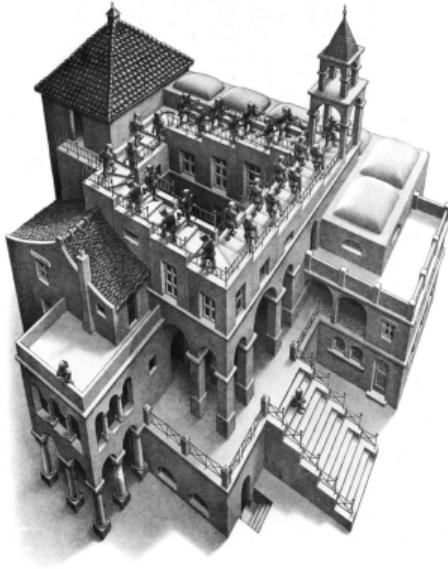
- ▶ The Bell table can be realised in the real world.
- ▶ So, what was our unwarranted assumption?
- ▶ That all variables could *in principle* be observed simultaneously.

The essence of contextuality

- ▶ Not all properties may be observed at once.
- ▶ Jointly observable properties provide **partial snapshots**.

The essence of contextuality

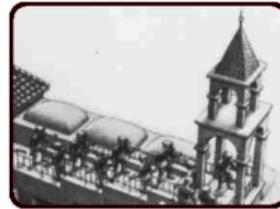
- ▶ Not all properties may be observed at once.
- ▶ Jointly observable properties provide **partial snapshots**.



M. C. Escher, *Ascending and Descending*

The essence of contextuality

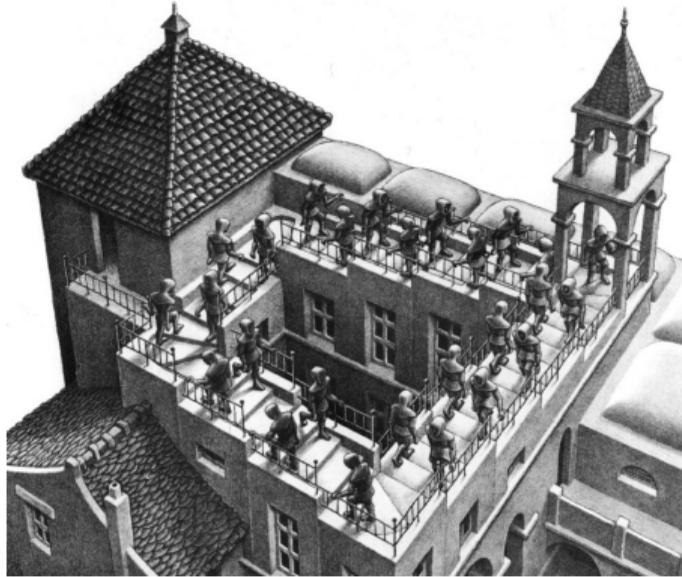
- ▶ Not all properties may be observed at once.
- ▶ Jointly observable properties provide **partial snapshots**.



Local consistency

The essence of contextuality

- ▶ Not all properties may be observed at once.
- ▶ Jointly observable properties provide **partial snapshots**.



Local consistency *but* **Global inconsistency**

Formalising empirical data

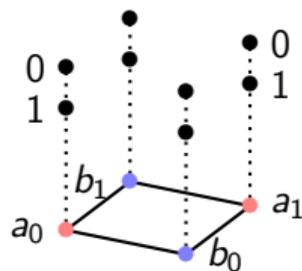
A **measurement scenario** $\mathbf{X} = \langle X, \Sigma, O \rangle$:

- ▶ X – a finite set of measurements
- ▶ Σ – a simplicial complex on X
faces are called the **measurement contexts**
- ▶ $O = (O_x)_{x \in X}$ – for each $x \in X$ a non-empty set of possible outcomes O_x

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	---	---	---	---
a_0	b_1	---	---	---	---
a_1	b_0	---	---	---	---
a_1	b_1	---	---	---	---

$$X = \{a_0, a_1, b_0, b_1\}, \quad O_x = \{0, 1\}$$

$$\Sigma = \downarrow \{ \{a_0, b_0\}, \{a_0, b_1\}, \{a_1, b_0\}, \{a_1, b_1\} \}.$$



Formalising empirical data

A **measurement scenario** $\mathbf{X} = \langle X, \Sigma, O \rangle$:

- ▶ X – a finite set of measurements
- ▶ Σ – a simplicial complex on X
faces are called the **measurement contexts**
- ▶ $O = (O_x)_{x \in X}$ – for each $x \in X$ a non-empty set of possible outcomes O_x

An **empirical model** $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on \mathbf{X} :

- ▶ each $e_\sigma \in \text{Prob}(\prod_{x \in \sigma} O_x)$ is a probability distribution over joint outcomes for σ .
- ▶ *generalised no-signalling* holds: for any $\sigma, \tau \in \Sigma$, if $\tau \subseteq \sigma$,

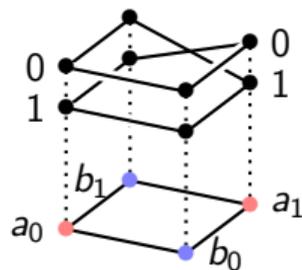
$$e_\sigma|_\tau = e_\tau$$

(i.e. marginals are well-defined)

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	1/2	0	0	1/2
a_0	b_1	1/2	0	0	1/2
a_1	b_0	1/2	0	0	1/2
a_1	b_1	0	1/2	1/2	0

$$X = \{a_0, a_1, b_0, b_1\}, O_x = \{0, 1\}$$

$$\Sigma = \downarrow \{ \{a_0, b_0\}, \{a_0, b_1\}, \{a_1, b_0\}, \{a_1, b_1\} \}.$$



Formalising empirical data

A **measurement scenario** $\mathbf{X} = \langle X, \Sigma, O \rangle$:

- ▶ X – a finite set of measurements
- ▶ Σ – a simplicial complex on X
faces are called the **measurement contexts**
- ▶ $O = (O_x)_{x \in X}$ – for each $x \in X$ a non-empty set of possible outcomes O_x

An **empirical model** $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on \mathbf{X} :

- ▶ each $e_\sigma \in \text{Prob}(\prod_{x \in \sigma} O_x)$ is a probability distribution over joint outcomes for σ .
- ▶ *generalised no-signalling* holds: for any $\sigma, \tau \in \Sigma$, if $\tau \subseteq \sigma$,

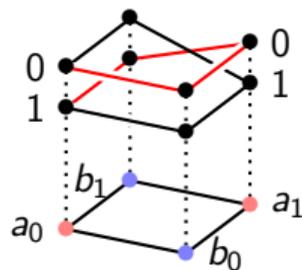
$$e_\sigma|_\tau = e_\tau$$

(i.e. marginals are well-defined)

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	1/2	0	0	1/2
a_0	b_1	1/2	0	0	1/2
a_1	b_0	1/2	0	0	1/2
a_1	b_1	0	1/2	1/2	0

$$X = \{a_0, a_1, b_0, b_1\}, O_x = \{0, 1\}$$

$$\Sigma = \downarrow \{ \{a_0, b_0\}, \{a_0, b_1\}, \{a_1, b_0\}, \{a_1, b_1\} \}.$$



Contextuality

An empirical model $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on a measurement scenario (X, Σ, O) is **non-contextual** if there is a distribution d on $\prod_{x \in X} O_x$ such that, for all $\sigma \in \Sigma$:

$$d|_\sigma = e_\sigma.$$

Contextuality

An empirical model $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on a measurement scenario (X, Σ, O) is **non-contextual** if there is a distribution d on $\prod_{x \in X} O_x$ such that, for all $\sigma \in \Sigma$:

$$d|_\sigma = e_\sigma.$$

That is, we can **glue** all the local information together into a global consistent description from which the local information can be recovered.

Contextuality

An empirical model $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on a measurement scenario (X, Σ, O) is **non-contextual** if there is a distribution d on $\prod_{x \in X} O_x$ such that, for all $\sigma \in \Sigma$:

$$d|_\sigma = e_\sigma.$$

That is, we can **glue** all the local information together into a global consistent description from which the local information can be recovered.

If no such global distribution exists, the empirical model is **contextual**.

Contextuality

An empirical model $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on a measurement scenario (X, Σ, O) is **non-contextual** if there is a distribution d on $\prod_{x \in X} O_x$ such that, for all $\sigma \in \Sigma$:

$$d|_\sigma = e_\sigma.$$

That is, we can **glue** all the local information together into a global consistent description from which the local information can be recovered.

If no such global distribution exists, the empirical model is **contextual**.

Contextuality: family of data that is **locally consistent** but **globally inconsistent**.

Contextuality

An empirical model $e = \{e_\sigma\}_{\sigma \in \Sigma}$ on a measurement scenario (X, Σ, O) is **non-contextual** if there is a distribution d on $\prod_{x \in X} O_x$ such that, for all $\sigma \in \Sigma$:

$$d|_\sigma = e_\sigma.$$

That is, we can **glue** all the local information together into a global consistent description from which the local information can be recovered.

If no such global distribution exists, the empirical model is **contextual**.

Contextuality: family of data that is **locally consistent** but **globally inconsistent**.

The import of Bell's and Kochen–Specker's theorems is that there are behaviours arising from quantum mechanics that are contextual.

Hierarchy of contextuality

Possibilistic collapse

- ▶ Given an empirical model e , define possibilistic model $\text{poss}(e)$ by taking the support of each distributions.

Hierarchy of contextuality

Possibilistic collapse

- ▶ Given an empirical model e , define possibilistic model $\text{poss}(e)$ by taking the support of each distributions.
- ▶ Contains the possibilistic, or logical, information of that model.

Hierarchy of contextuality

Possibilistic collapse

- ▶ Given an empirical model e , define possibilistic model $\text{poss}(e)$ by taking the support of each distributions.
- ▶ Contains the possibilistic, or logical, information of that model.

A	B	(0,0)	(0,1)	(1,0)	(1,1)		A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1/2	0	0	1/2		a_0	b_0	1	0	0	1
a_0	b_1	3/8	1/8	1/8	3/8	→	a_0	b_1	1	1	1	1
a_1	b_0	3/8	1/8	1/8	3/8		a_1	b_0	1	1	1	1
a_1	b_1	1/8	3/8	3/8	1/8		a_1	b_1	1	1	1	1

Hierarchy of contextuality

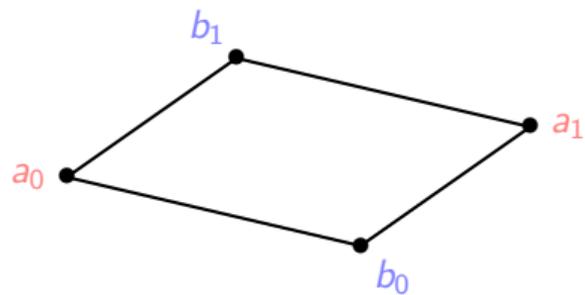
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

Hierarchy of contextuality

Hardy model

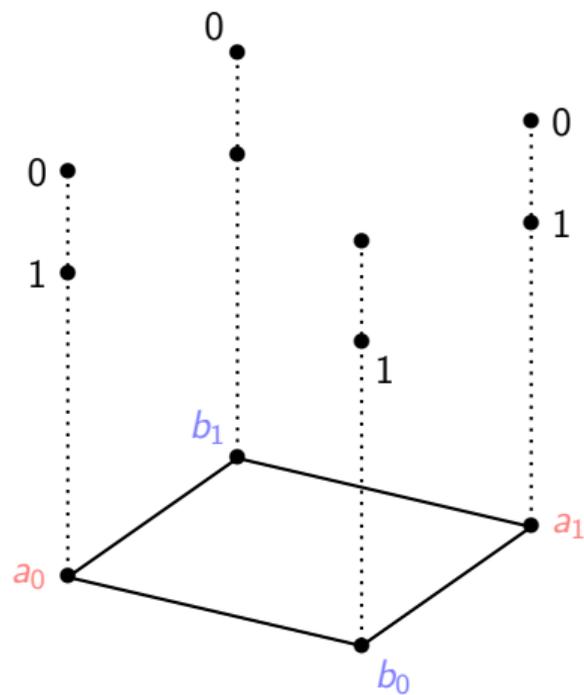
A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0



Hierarchy of contextuality

Hardy model

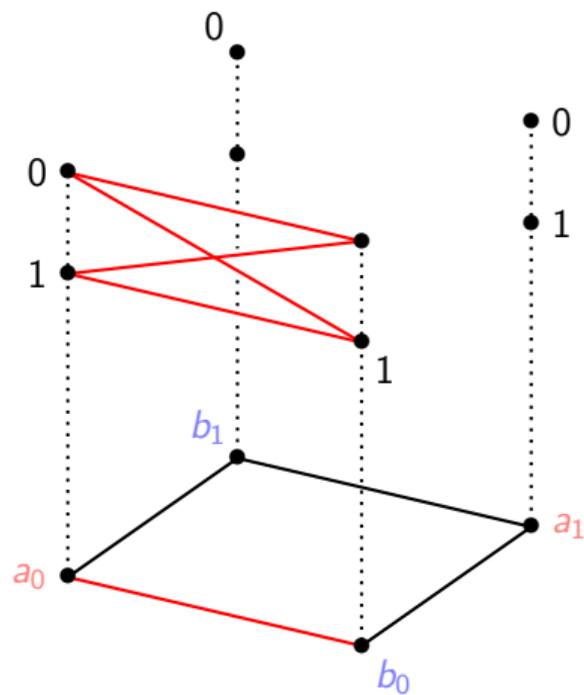
A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0



Hierarchy of contextuality

Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

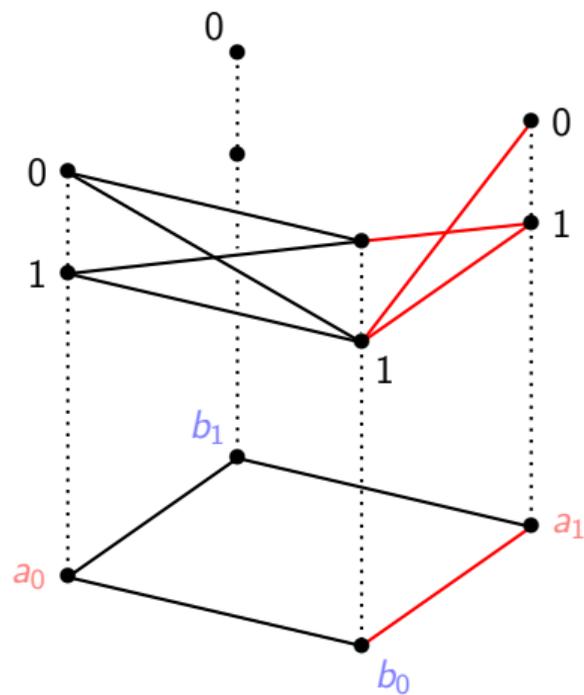


Hierarchy of contextuality

Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0$$



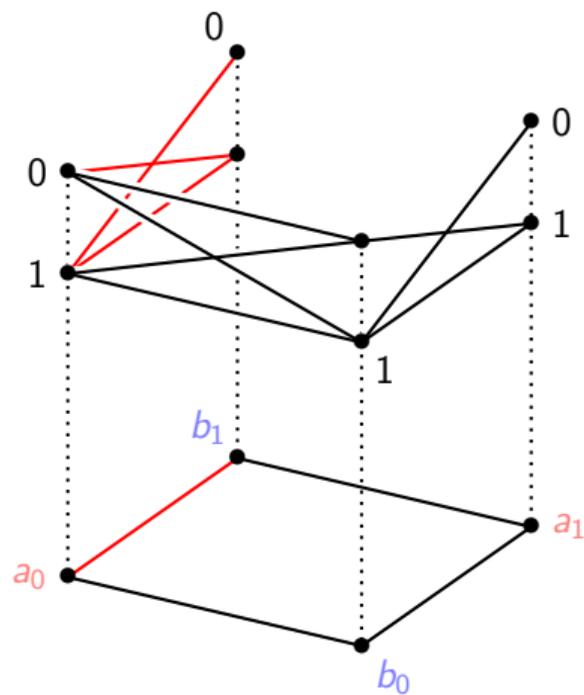
Hierarchy of contextuality

Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0$$

$$a_0 \vee b_1$$



Hierarchy of contextuality

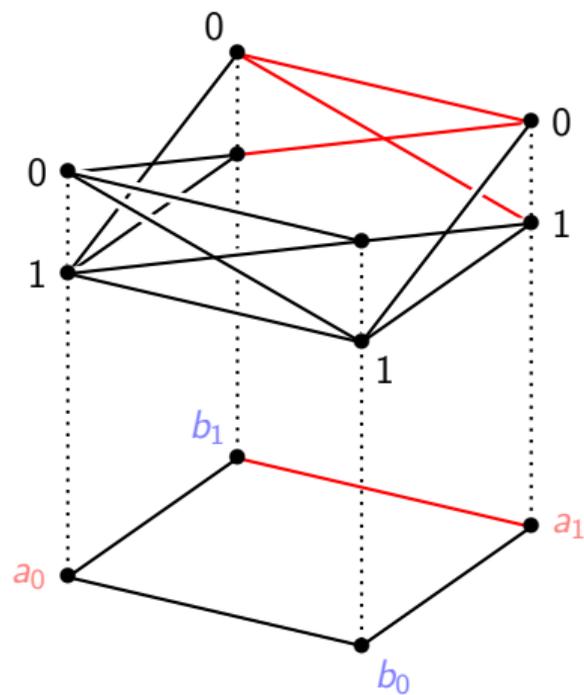
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0$$

$$a_0 \vee b_1$$

$$\neg(a_1 \wedge b_1)$$



Hierarchy of contextuality

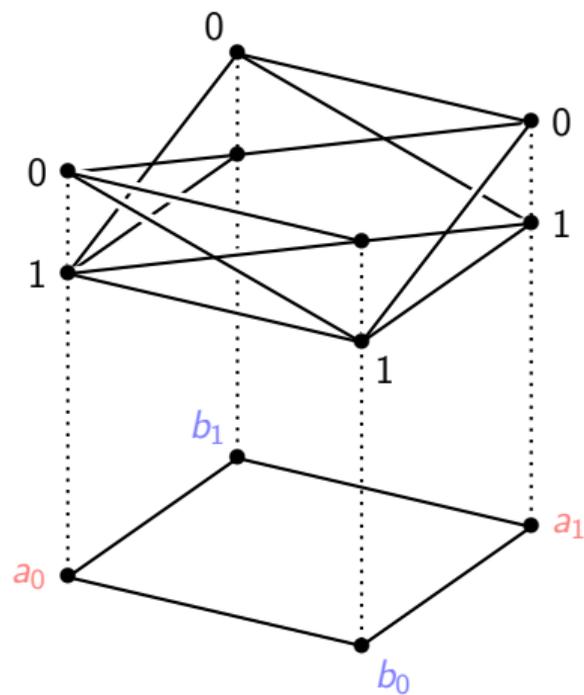
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0$$

$$a_0 \vee b_1$$

$$\neg(a_1 \wedge b_1)$$



Hierarchy of contextuality

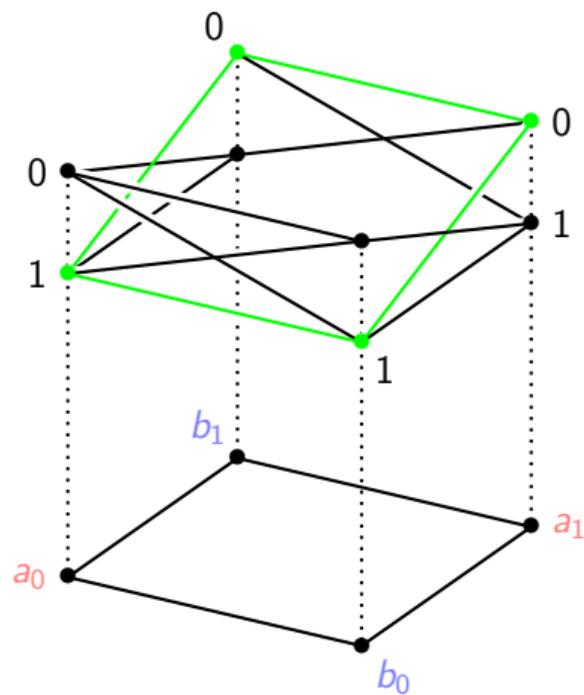
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0$$

$$a_0 \vee b_1$$

$$\neg(a_1 \wedge b_1)$$



There are some global sections,

Classical assignment: $[a_0 \mapsto 1, a_1 \mapsto 0, b_0 \mapsto 1, b_1 \mapsto 0]$

Hierarchy of contextuality

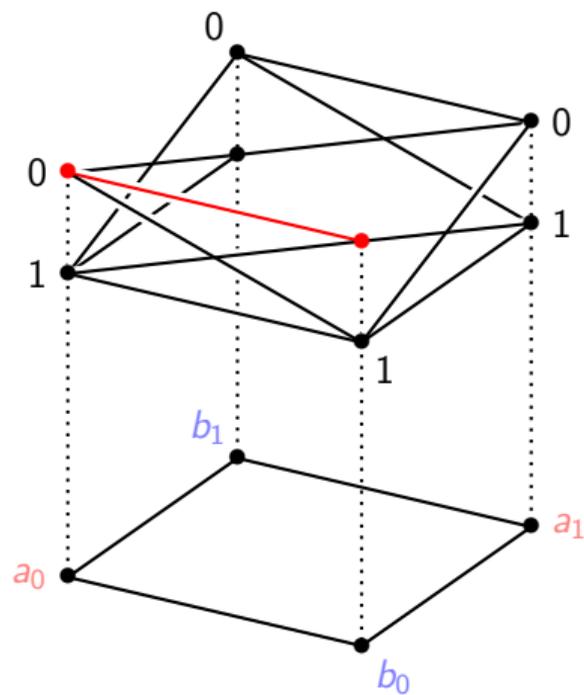
Hardy model

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

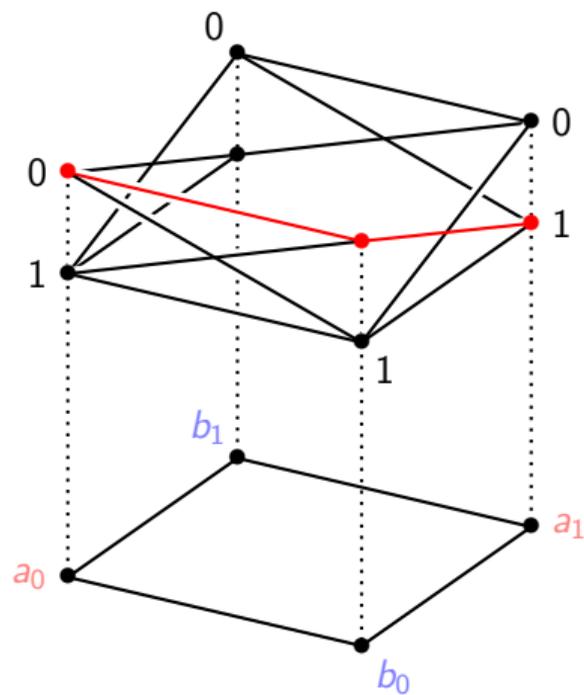
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

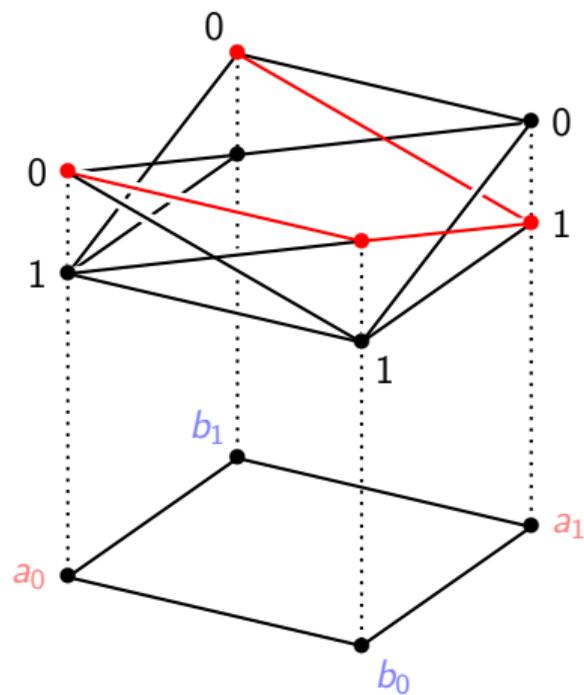
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

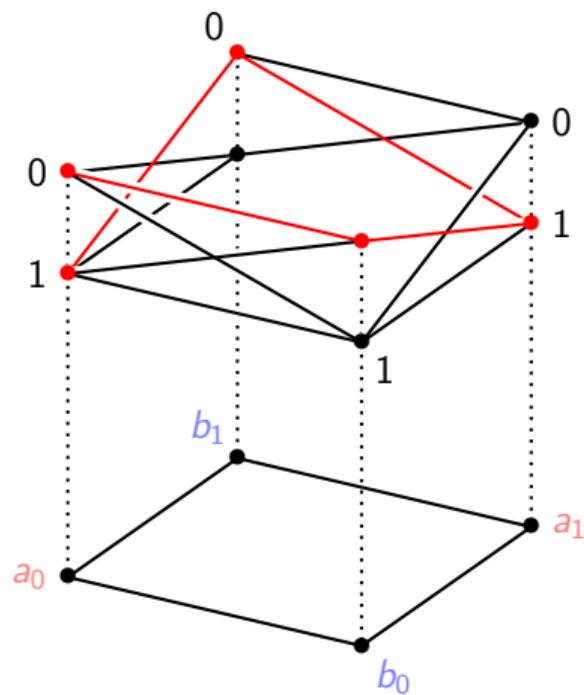
Hardy model

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

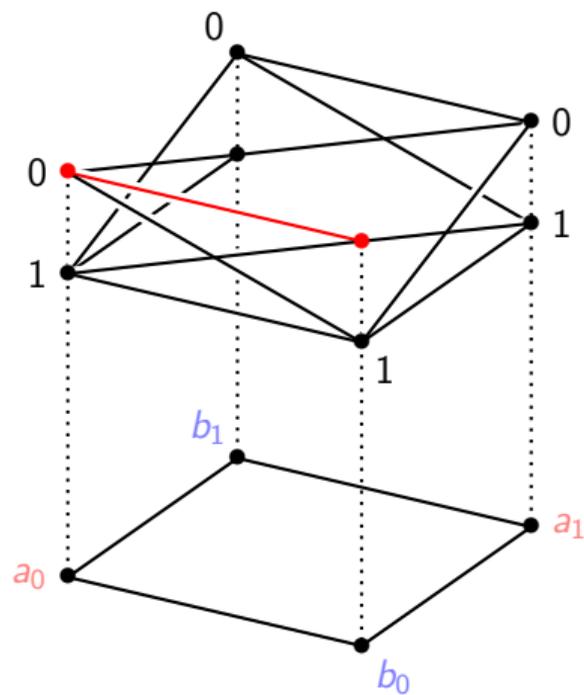
Hardy model

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

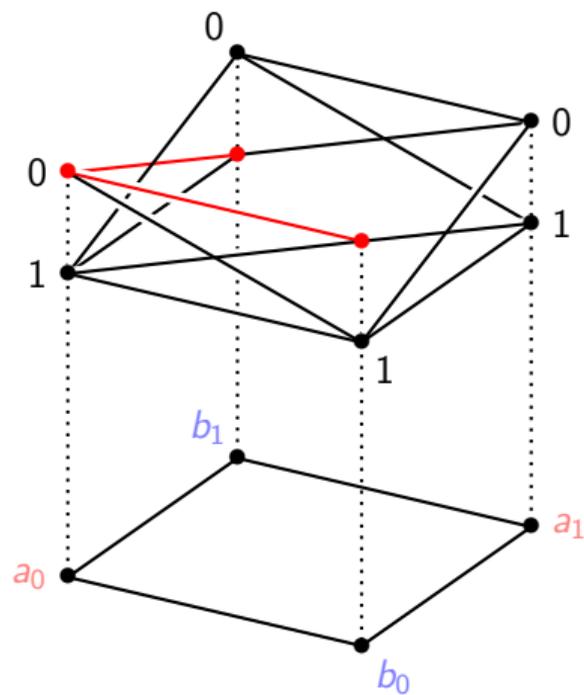
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

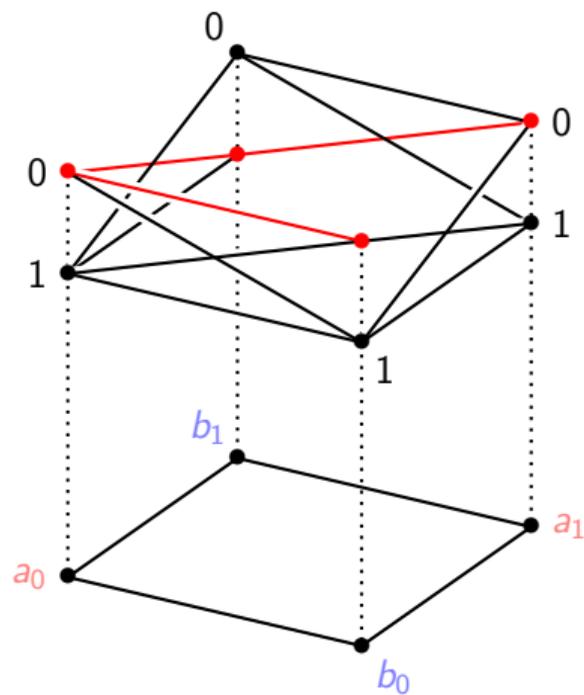
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

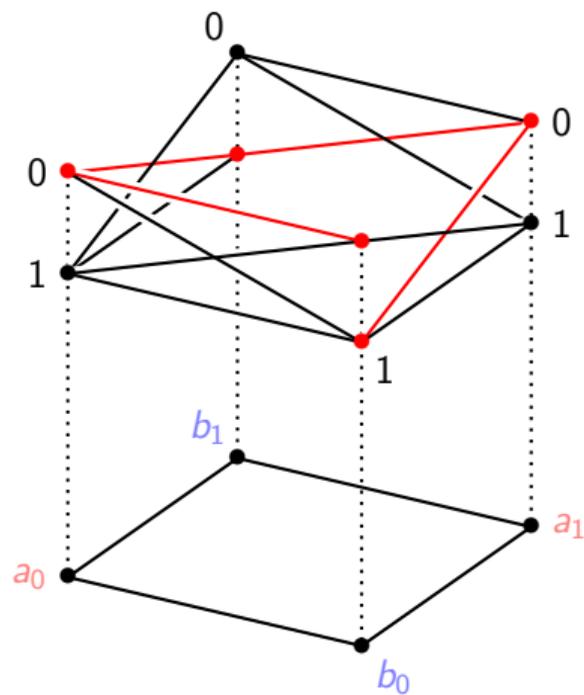
Hardy model

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...



Hierarchy of contextuality

Hardy model

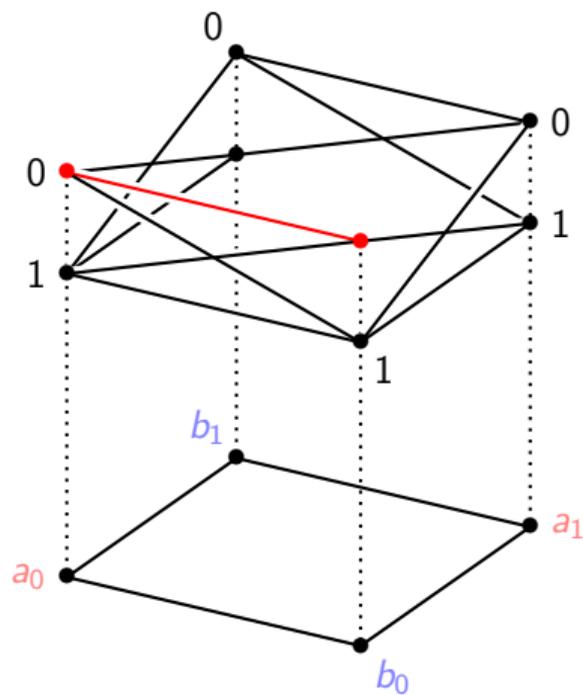
A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	1	1	1
a_0	b_1	0	1	1	1
a_1	b_0	0	1	1	1
a_1	b_1	1	1	1	0

$$a_1 \vee b_0 \quad a_0 \vee b_1 \quad \neg(a_1 \wedge b_1)$$

$$[a_0 \mapsto 0, b_0 \mapsto 0]$$

There are some global sections, but ...

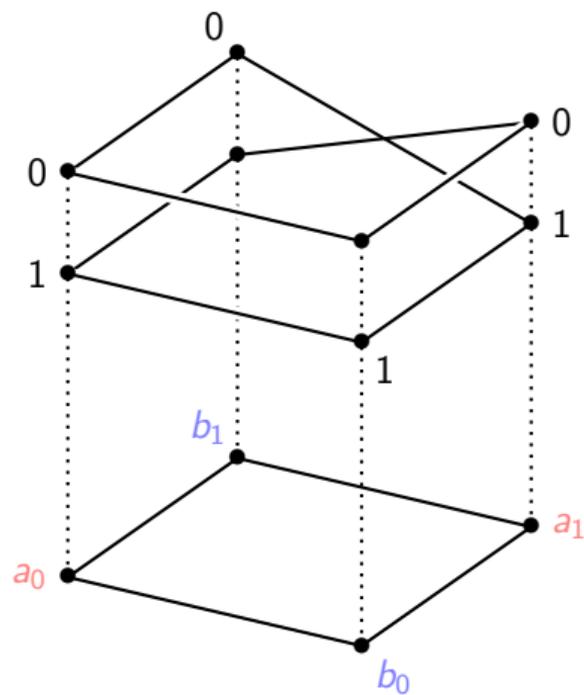
Logical contextuality: Not all sections extend to global ones.



Hierarchy of contextuality

Popescu–Rohrlich box

A	B	(0,0)	(0,1)	(1,0)	(1,1)
a_0	b_0	1	0	0	1
a_0	b_1	1	0	0	1
a_1	b_0	1	0	0	1
a_1	b_1	0	1	1	0



Strong contextuality:

no event can be extended to a global assignment.

$$a_0 \leftrightarrow b_0 \quad a_0 \leftrightarrow b_1 \quad a_1 \leftrightarrow b_0 \quad a_1 \oplus b_1$$

Measuring Contextuality

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions** $c \in \text{SubProb}(O^X)$ such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

Non-contextual fraction: maximum weight of such a subdistribution.

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions** $c \in \text{SubProb}(O^X)$ such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

Non-contextual fraction: maximum weight of such a subdistribution.

Equivalently, maximum weight λ over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e'$$

where e^{NC} is a non-contextual model.

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions** $c \in \text{SubProb}(O^X)$ such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

Non-contextual fraction: maximum weight of such a subdistribution.

Equivalently, maximum weight λ over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e'$$

where e^{NC} is a non-contextual model.

The contextual fraction

Non-contextuality: global distribution $d \in \text{Prob}(O^X)$ such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions** $c \in \text{SubProb}(O^X)$ such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

Non-contextual fraction: maximum weight of such a subdistribution.

Equivalently, maximum weight λ over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e^{SC}$$

where e^{NC} is a non-contextual model. e^{SC} is strongly contextual!

$$\text{NCF}(e) = \lambda \quad \text{CF}(e) = 1 - \lambda$$

Generalised Bell inequalities

An **inequality** for a scenario $\langle X, \mathcal{M}, O \rangle$ is given by:

- ▶ a set of coefficients $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound R

Generalised Bell inequalities

An **inequality** for a scenario $\langle X, \mathcal{M}, O \rangle$ is given by:

- ▶ a set of coefficients $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound R

For a model e , the inequality reads as

$$\mathcal{B}_\alpha(e) \leq R ,$$

where

$$\mathcal{B}_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s) .$$

Generalised Bell inequalities

An **inequality** for a scenario $\langle X, \mathcal{M}, O \rangle$ is given by:

- ▶ a set of coefficients $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound R

For a model e , the inequality reads as

$$\mathcal{B}_\alpha(e) \leq R ,$$

where

$$\mathcal{B}_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s) .$$

Wlog we can take R non-negative (in fact, we can take $R = 0$).

Generalised Bell inequalities

An **inequality** for a scenario $\langle X, \mathcal{M}, O \rangle$ is given by:

- ▶ a set of coefficients $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound R

For a model e , the inequality reads as

$$\mathcal{B}_\alpha(e) \leq R ,$$

where

$$\mathcal{B}_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s) .$$

Wlog we can take R non-negative (in fact, we can take $R = 0$).

It is called a **Bell inequality** if it is satisfied by every NC model. If it is saturated by some NC model, the Bell inequality is said to be **tight**.

Generalised Bell inequalities

An **inequality** for a scenario $\langle X, \mathcal{M}, O \rangle$ is given by:

- ▶ a set of coefficients $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound R

For a model e , the inequality reads as

$$\mathcal{B}_\alpha(e) \leq R ,$$

where

$$\mathcal{B}_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s) .$$

Wlog we can take R non-negative (in fact, we can take $R = 0$).

It is called a **Bell inequality** if it is satisfied by every NC model. If it is saturated by some NC model, the Bell inequality is said to be **tight**.

NB: A complete set of inequalities can be derived from the logical approach.

Violation of a Bell inequality

A Bell inequality establishes a bound for the value of $\mathcal{B}_\alpha(e)$ amongst NC models.

Violation of a Bell inequality

A Bell inequality establishes a bound for the value of $\mathcal{B}_\alpha(e)$ amongst NC models.

For a general (no-signalling) model e , the quantity is limited only by

$$\|\alpha\| := \sum_{C \in \mathcal{M}} \max \{ \alpha(C, s) \mid s \in \mathcal{O}^C \}$$

Violation of a Bell inequality

A Bell inequality establishes a bound for the value of $\mathcal{B}_\alpha(e)$ amongst NC models.

For a general (no-signalling) model e , the quantity is limited only by

$$\|\alpha\| := \sum_{C \in \mathcal{M}} \max \{ \alpha(C, s) \mid s \in \mathcal{O}^C \}$$

The **normalised violation** of a Bell inequality $\langle \alpha, R \rangle$ by an empirical model e is the value

$$\frac{\max\{0, \mathcal{B}_\alpha(e) - R\}}{\|\alpha\| - R} .$$

Bell inequality violation and the contextual fraction

Proposition

Let e be an empirical model.

Bell inequality violation and the contextual fraction

Proposition

Let e be an empirical model.

- ▶ The normalised violation by e of any Bell inequality is at most $CF(e)$.

Bell inequality violation and the contextual fraction

Proposition

Let e be an empirical model.

- ▶ The normalised violation by e of any Bell inequality is at most $CF(e)$.
- ▶ This bound is attained: there exists a Bell inequality whose normalised violation by e is exactly $CF(e)$.

Bell inequality violation and the contextual fraction

Proposition

Let e be an empirical model.

- ▶ The normalised violation by e of any Bell inequality is at most $CF(e)$.
- ▶ This bound is attained: there exists a Bell inequality whose normalised violation by e is exactly $CF(e)$.
- ▶ Moreover, this Bell inequality is tight at “the” non-contextual model e^{NC} and maximally violated by “the” strongly contextual model e^{SC} for any decomposition:

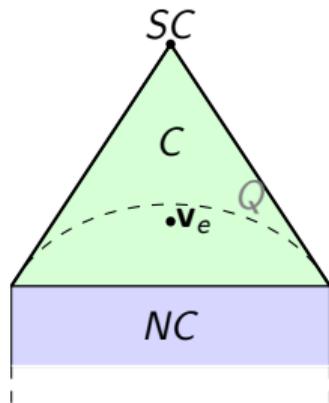
$$e = NCF(e)e^{NC} + CF(e)e^{SC} .$$

Bell inequality violation and the contextual fraction

Quantifying Contextuality LP:

Find $\mathbf{c} \in \mathbb{R}^n$
maximising $\mathbf{1} \cdot \mathbf{c}$
subject to $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$
and $\mathbf{c} \geq \mathbf{0}$.

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$ with $\lambda = \mathbf{1} \cdot \mathbf{x}^*$.



Bell inequality violation and the contextual fraction

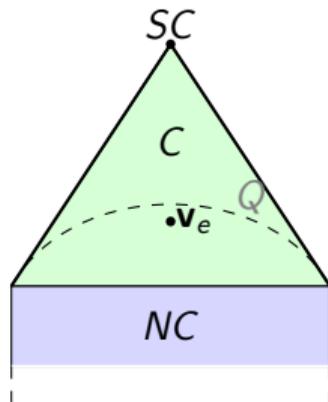
Quantifying Contextuality LP:

Find $\mathbf{c} \in \mathbb{R}^n$
maximising $\mathbf{1} \cdot \mathbf{c}$
subject to $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$
and $\mathbf{c} \geq \mathbf{0}$.

Dual LP:

Find $\mathbf{y} \in \mathbb{R}^m$
minimising $\mathbf{y} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$
and $\mathbf{y} \geq \mathbf{0}$.

$$e = \lambda e^{NC} + (1 - \lambda) e^{SC} \text{ with } \lambda = \mathbf{1} \cdot \mathbf{x}^* .$$



Bell inequality violation and the contextual fraction

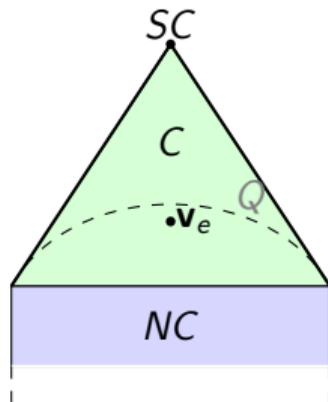
Quantifying Contextuality LP:

Find $\mathbf{c} \in \mathbb{R}^n$
maximising $\mathbf{1} \cdot \mathbf{c}$
subject to $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$
and $\mathbf{c} \geq \mathbf{0}$.

Dual LP:

Find $\mathbf{y} \in \mathbb{R}^m$
minimising $\mathbf{y} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$
and $\mathbf{y} \geq \mathbf{0}$.

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$ with $\lambda = \mathbf{1} \cdot \mathbf{x}^*$.



$$\mathbf{a} := \mathbf{1} - |\mathcal{M}|\mathbf{y}$$

Bell inequality violation and the contextual fraction

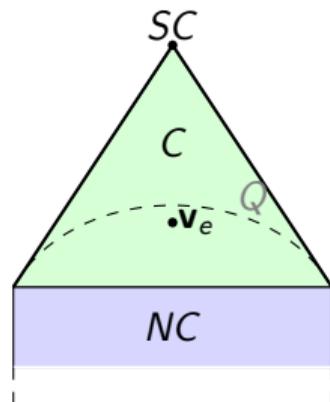
Quantifying Contextuality LP:

Find $\mathbf{c} \in \mathbb{R}^n$
maximising $\mathbf{1} \cdot \mathbf{c}$
subject to $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$
and $\mathbf{c} \geq \mathbf{0}$.

Dual LP:

Find $\mathbf{y} \in \mathbb{R}^m$
minimising $\mathbf{y} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$
and $\mathbf{y} \geq \mathbf{0}$.

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$ with $\lambda = \mathbf{1} \cdot \mathbf{x}^*$.



$$\mathbf{a} := \mathbf{1} - |\mathcal{M}|\mathbf{y}$$

Find $\mathbf{a} \in \mathbb{R}^m$
maximising $\mathbf{a} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{a} \leq \mathbf{0}$
and $\mathbf{a} \leq \mathbf{1}$.

Bell inequality violation and the contextual fraction

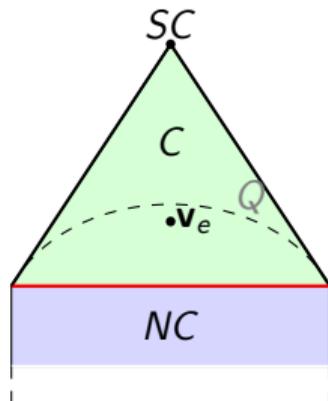
Quantifying Contextuality LP:

Find $\mathbf{c} \in \mathbb{R}^n$
maximising $\mathbf{1} \cdot \mathbf{c}$
subject to $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$
and $\mathbf{c} \geq \mathbf{0}$.

Dual LP:

Find $\mathbf{y} \in \mathbb{R}^m$
minimising $\mathbf{y} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$
and $\mathbf{y} \geq \mathbf{0}$.

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$ with $\lambda = \mathbf{1} \cdot \mathbf{x}^*$.



$$\mathbf{a} := \mathbf{1} - |\mathcal{M}|\mathbf{y}$$

Find $\mathbf{a} \in \mathbb{R}^m$
maximising $\mathbf{a} \cdot \mathbf{v}^e$
subject to $\mathbf{M}^T \mathbf{a} \leq \mathbf{0}$
and $\mathbf{a} \leq \mathbf{1}$.

computes tight Bell inequality
(separating hyperplane)

Contextuality as a resource

Contextuality and advantage in quantum computation

- ▶ Measurement-based quantum computation (MBQC)
 - ‘*Contextuality in measurement-based quantum computation*’
Raussendorf, Physical Review A, 2013.
- ▶ Magic state distillation
 - ‘*Contextuality supplies the ‘magic’ for quantum computation*’
Howard, Wallman, Veitch, Emerson, Nature, 2014.
- ▶ Shallow circuits
 - ‘*Quantum advantage with shallow circuits*’
Bravyi, Gossett, Koenig, Science, 2018.
 - ▶ Contextuality analysis: Aasnæss, Forthcoming, 2019.

Overview: Contextuality as a resource

- ▶ Our focus is on contextuality as a **resource**:
 - ▶ how can we use it, what can we do with it?

Overview: Contextuality as a resource

- ▶ Our focus is on contextuality as a **resource**:
 - ▶ how can we use it, what can we do with it?
- ▶ From this perspective, we want to compare contextual behaviours:
 - ▶ When is one a more powerful resource than another?
 - ▶ When are two behaviours essentially the same?

Overview: Contextuality as a resource

- ▶ Our focus is on contextuality as a **resource**:
 - ▶ how can we use it, what can we do with it?
- ▶ From this perspective, we want to compare contextual behaviours:
 - ▶ When is one a more powerful resource than another?
 - ▶ When are two behaviours essentially the same?

Example

'Popescu-Rohrlich correlations as a unit of nonlocality'

Barrett, Pironio, Physical Review Letters, 2005.

- ▶ PR boxes simulate all 2-outcome bipartite boxes
- ▶ A tripartite quantum box that cannot be simulated from PR boxes

Structure of resources

Two perspectives:

Structure of resources

Two perspectives:

1. **Resource theories** (coming from Physics):

Algebraic theory of '**free operations**' that do not introduce more of the resource in question.

Resource B can be obtained from resource A if it can be built from A using free operations.

'Contextual fraction as a measure of contextuality', Abramsky, B, Mansfield, PRL, 2017.

'Noncontextual wirings', Amaral, Cabello, Terra Cunha, Aolita, PRL, 2018.

Structure of resources

Two perspectives:

1. **Resource theories** (coming from Physics):

Algebraic theory of '**free operations**' that do not introduce more of the resource in question.

Resource B can be obtained from resource A if it can be built from A using free operations.

'Contextual fraction as a measure of contextuality', Abramsky, B, Mansfield, PRL, 2017.

'Noncontextual wirings', Amaral, Cabello, Terra Cunha, Aolita, PRL, 2018.

2. **Simulations or reducibility** (coming from Computer Science):

Notion of **simulation** between behaviours of systems.

One resource can be reduced to another if it can be simulated by it.

Cf. (in)computability, degrees of unsolvability, complexity classes.

'Categories of empirical models', Karvonen, QPL 2018.

Free operations

- ▶ We think of empirical models as black boxes

Free operations

- ▶ We think of empirical models as black boxes
- ▶ What operations can we perform (*non-contextually*) on them?

Free operations

- ▶ **Zero model** z : unique empirical model on the empty measurement scenario

$$\langle \emptyset, \Delta_0 = \{\emptyset\}, () \rangle .$$

- ▶ **Singleton model** u : unique empirical model on the 1-outcome 1-measurement scenario

$$\langle \mathbf{1} = \{\star\}, \Delta_1 = \{\emptyset, \mathbf{1}\}, (O_\star = \mathbf{1}) \rangle .$$

- ▶ **Probabilistic mixing**: Given empirical models e and d in $\langle X, \Sigma, O \rangle$ and $\lambda \in [0, 1]$, the model $e +_\lambda d : \langle X, \Sigma, O \rangle$ is given by the mixture $\lambda e + (1 - \lambda)d$.

Free operations

- ▶ **Tensor:** Let $e : \langle X, \Sigma, O \rangle$ and $d : \langle Y, \Delta, P \rangle$. Then

$$e \otimes d : \langle X \sqcup Y, \Sigma * \Delta, [O, P] \rangle$$

where $\Sigma * \Theta := \{\sigma \cup \tau \mid \sigma \in \Sigma, \tau \in \Theta\}$. *Runs e and d independently and in parallel.*

- ▶ **Coarse-graining:** Given $e : \langle X, \Sigma, O \rangle$ and a family of functions $h = (h_x : O_x \rightarrow O'_x)_{x \in X}$, get a coarse-grained model

$$e/h : \langle X, \Sigma, O' \rangle$$

.

- ▶ **Measurement translation:** Given $e : \langle X, \Sigma, O \rangle$ and a simplicial map $f : \Sigma' \rightarrow \Sigma$, the model $f^*e : \langle X', \Sigma', O \rangle$ is defined by pulling e back along the map f .

New free operation

- ▶ **Conditioning on a measurement:** Given $e : \langle X, \Sigma, O \rangle$, $x \in X$ and a family of measurements $(y_o)_{o \in O_x}$ with $y_o \in \text{Vert}(\text{lk}_x \Sigma)$. Consider a new measurement $x?(y_o)_{o \in O_x}$, abbreviated $x?y$. Get

$$e[x?y] : \langle X \cup \{x?y\}, \Sigma[x?y], O[x?y \mapsto O_{x?y}] \rangle$$

that results from adding $x?y$ to e .

If Σ is a simplicial complex and a $\sigma \in \Sigma$ is a face, the **link** of σ in Σ is the subcomplex of Σ whose faces are

$$\text{lk}_\sigma \Sigma := \{ \tau \in \Sigma \mid \sigma \cap \tau = \emptyset, \sigma \cup \tau \in \Sigma \} .$$

What contexts are still available once the measurements in σ have been performed.

Free operations

Free operations generate terms typed by measurement scenarios:

$$\begin{aligned} \text{Terms } \ni t \quad ::= & \ v \in \text{Var} \mid z \mid u \mid f^*t \mid t/h \\ & \mid t +_{\lambda} t \mid t \otimes t \mid t[x?y] \end{aligned}$$

Free operations

Free operations generate terms typed by measurement scenarios:

$$\begin{aligned} \text{Terms } \ni t \quad ::= & \ v \in \text{Var} \mid z \mid u \mid f^*t \mid t/h \\ & \mid t +_{\lambda} t \mid t \otimes t \mid t[x?y] \end{aligned}$$

Terms without variables represent noncontextual empirical models.

Conversely, every noncontextual model can be represented by a term without variables.

Free operations

Free operations generate terms typed by measurement scenarios:

$$\begin{aligned} \text{Terms } \ni t \quad ::= & \ v \in \text{Var} \mid z \mid u \mid f^*t \mid t/h \\ & \mid t +_{\lambda} t \mid t \otimes t \mid t[x?y] \end{aligned}$$

Terms without variables represent noncontextual empirical models.

Conversely, every noncontextual model can be represented by a term without variables.

Can d be transformed to e ?

Formally: is there a typed term $v : \langle Y, \Delta, P \rangle \vdash t : \langle X, \Sigma, O \rangle$ such that $t[d/v] = e$?

Contextual fraction is a monotone

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Contextual fraction is a monotone

Relabelling $e[\alpha]$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $e \upharpoonright \mathcal{M}'$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining e/f

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining $CF(e/f) \leq CF(e)$

Mixing $\lambda e + (1 - \lambda)e'$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining $CF(e/f) \leq CF(e)$

Mixing $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice $e \& e'$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining $CF(e/f) \leq CF(e)$

Mixing $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice $CF(e \& e') = \max\{CF(e), CF(e')\}$

Tensor $e_1 \otimes e_2$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining $CF(e/f) \leq CF(e)$

Mixing $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice $CF(e \& e') = \max\{CF(e), CF(e')\}$

Tensor $CF(e_1 \otimes e_2) = CF(e_1) + CF(e_2) - CF(e_1)CF(e_2)$

$$NCF(e_1 \otimes e_2) = NCF(e_1) NCF(e_2)$$

Conditional $e[x?y]$

Contextual fraction is a monotone

Relabelling $CF(e[\alpha]) = CF(e)$

Restriction $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining $CF(e/f) \leq CF(e)$

Mixing $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice $CF(e \& e') = \max\{CF(e), CF(e')\}$

Tensor $CF(e_1 \otimes e_2) = CF(e_1) + CF(e_2) - CF(e_1)CF(e_2)$

$NCF(e_1 \otimes e_2) = NCF(e_1) NCF(e_2)$

Conditional $CF(e[x?y]) = CF(e)$

Contextual fraction and quantum advantages

Contextual fraction and advantages

- ▶ Contextuality has been associated with quantum advantage in information-processing and computational tasks.

Contextual fraction and advantages

- ▶ Contextuality has been associated with quantum advantage in information-processing and computational tasks.
- ▶ Measure of contextuality \rightsquigarrow **quantify such advantages.**

Contextual fraction and cooperative games

- ▶ Game described by n formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.

Contextual fraction and cooperative games

- ▶ Game described by n formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.
- ▶ If the formulae are k -consistent (at most k are jointly satisfiable), **hardness of the task** is $\frac{n-k}{n}$.

'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

Contextual fraction and cooperative games

- ▶ Game described by n formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.
- ▶ If the formulae are k -consistent (at most k are jointly satisfiable), **hardness of the task** is $\frac{n-k}{n}$.
'Logical Bell inequalities', Abramsky, Hardy, Physical Review A, 2012.

- ▶ We have

$$1 - \bar{p}_S \geq \text{NCF} \frac{n-k}{n}$$

Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme
(m input bits, l output bits, n parties)

Contextuality and MBQC

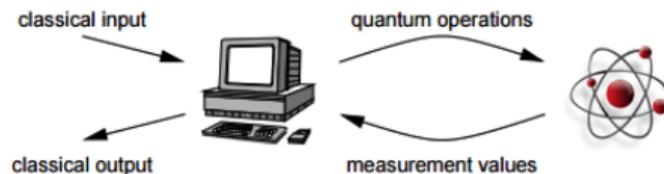
E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme
(m input bits, l output bits, n parties)
 - ▶ classical control:
 - ▶ pre-processes input
 - ▶ determines the flow of measurements
 - ▶ post-processes to produce the output
- only \mathbb{Z}_2 -linear computations.

Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme (m input bits, l output bits, n parties)
 - ▶ classical control:
 - ▶ pre-processes input
 - ▶ determines the flow of measurements
 - ▶ post-processes to produce the output
- only \mathbb{Z}_2 -linear computations.
- ▶ additional power to compute non-linear functions resides in resource empirical models.



Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme (m input bits, l output bits, n parties)
- ▶ classical control:
 - ▶ pre-processes input
 - ▶ determines the flow of measurements
 - ▶ post-processes to produce the outputonly \mathbb{Z}_2 -linear computations.
- ▶ additional power to compute non-linear functions resides in resource empirical models.

Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme (m input bits, l output bits, n parties)
 - ▶ classical control:
 - ▶ pre-processes input
 - ▶ determines the flow of measurements
 - ▶ post-processes to produce the output
- only \mathbb{Z}_2 -linear computations.
- ▶ additional power to compute non-linear functions resides in resource empirical models.
 - ▶ Raussendorf (2013): If an ℓ_2 -MBQC **deterministically** computes a non-linear Boolean function $f : 2^m \rightarrow 2^l$ then the resource must be **strongly contextual**.

Contextuality and MBQC

E.g. Raussendorf (2013) ℓ_2 -MBQC

- ▶ measurement-based quantum computing scheme
(m input bits, l output bits, n parties)

- ▶ classical control:

- ▶ pre-processes input
- ▶ determines the flow of measurements
- ▶ post-processes to produce the output

only \mathbb{Z}_2 -linear computations.

- ▶ additional power to compute non-linear functions resides in resource empirical models.

- ▶ Raussendorf (2013): If an ℓ_2 -MBQC **deterministically** computes a non-linear Boolean function $f : 2^m \rightarrow 2^l$ then the resource must be **strongly contextual**.

- ▶ Probabilistic version: non-linear function computed with sufficiently large probability of success implies contextuality.

Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function $f : 2^m \rightarrow 2^l$ using ℓ_2 -MBQC

Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function $f : 2^m \rightarrow 2^l$ using ℓ_2 -MBQC
- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between f and closest \mathbb{Z}_2 -linear function)

where for Boolean functions f and g , $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$.

Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function $f : 2^m \rightarrow 2^l$ using ℓ_2 -MBQC

- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between f and closest \mathbb{Z}_2 -linear function)

where for Boolean functions f and g , $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$.

- ▶ **Average probability of success** computing f (over all 2^m possible inputs): \bar{p}_S .

Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function $f : 2^m \rightarrow 2^l$ using ℓ_2 -MBQC

- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between f and closest \mathbb{Z}_2 -linear function)

where for Boolean functions f and g , $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$.

- ▶ **Average probability of success** computing f (over all 2^m possible inputs): \bar{p}_S .

- ▶ Then,

$$1 - \bar{p}_S \geq \text{NCF}(e) \nu(f)$$

Questions...

?