

# The contextual fraction and contextuality as a resource



Samson Abramsky<sup>1</sup>



Rui Soares Barbosa<sup>1</sup>



Shane Mansfield<sup>2</sup>

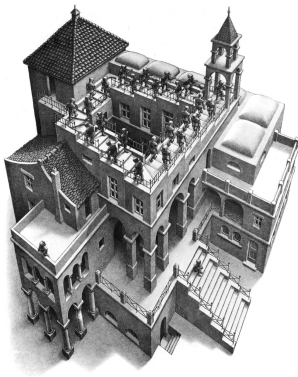
<sup>1</sup>Department of Computer Science, University of Oxford  
`{samson.abramsky,rui.soares.barbosa}@cs.ox.ac.uk`

<sup>2</sup>School of Informatics, University of Edinburgh  
`shane.mansfield@ed.ac.uk`

Foundations of Quantum Mechanics and Technology  
Linnéuniversitetet, Växjö, 13th June 2017

# Motivation

- **Contextuality**: a fundamental non-classical phenomenon of QM



# Motivation

- ▶ **Contextuality**: a fundamental non-classical phenomenon of QM
- ▶ Contextuality as a **resource** for QIP and QC:

# Motivation

- ▶ **Contextuality**: a fundamental non-classical phenomenon of QM
- ▶ Contextuality as a **resource** for QIP and QC:
  - ▶ **Non-local games**
    - XOR games (CHSH; Cleve, Høyer, Toner, & Watrous)
    - quantum graph homomorphisms (Mančinska & Roberson)
    - constraint satisfaction (Cleve & Mittal)
    - etc. (Abramsky, B, de Silva, & Zapata)

# Motivation

- ▶ **Contextuality**: a fundamental non-classical phenomenon of QM
- ▶ Contextuality as a **resource** for QIP and QC:
  - ▶ **Non-local games**  
XOR games (CHSH; Cleve, Høyer, Toner, & Watrous)  
quantum graph homomorphisms (Mančinska & Roberson)  
constraint satisfaction (Cleve & Mittal)  
etc. (Abramsky, B, de Silva, & Zapata)
  - ▶ **MBQC**  
Raussendorf (2013)  
“Contextuality in measurement-based quantum computation”

# Motivation

- ▶ **Contextuality**: a fundamental non-classical phenomenon of QM
- ▶ Contextuality as a **resource** for QIP and QC:
  - ▶ **Non-local games**  
XOR games (CHSH; Cleve, Høyer, Toner, & Watrous)  
quantum graph homomorphisms (Mančinska & Roberson)  
constraint satisfaction (Cleve & Mittal)  
etc. (Abramsky, B, de Silva, & Zapata)
  - ▶ **MBQC**  
Raussendorf (2013)  
“Contextuality in measurement-based quantum computation”
  - ▶ **MSD**  
Howard, Wallman, Veith, & Emerson (2014)  
“Contextuality supplies the ‘magic’ for quantum computation”

# Motivation

- ▶ Abramsky & Brandenburger:  
unified framework for non-locality and contextuality

# Motivation

- ▶ Abramsky & Brandenburger:  
unified framework for non-locality and contextuality
- ▶ qualitative hierarchy of contextuality for empirical models



# Motivation

- ▶ Abramsky & Brandenburger:  
unified framework for non-locality and contextuality
- ▶ qualitative hierarchy of contextuality for empirical models
- ▶ quantitative grading – **measure of contextuality**  
(NB: there may be more than one useful measure)

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

- ▶ **General**, i.e. applicable to any measurement scenario

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

- ▶ **General**, i.e. applicable to any measurement scenario
- ▶ **Normalised**, allowing comparison across scenarios  
0 for non-contextuality . . . 1 for strong contextuality

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

- ▶ **General**, i.e. applicable to any measurement scenario
- ▶ **Normalised**, allowing comparison across scenarios  
0 for non-contextuality . . . 1 for strong contextuality
- ▶ Computable using **linear programming**

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

- ▶ **General**, i.e. applicable to any measurement scenario
- ▶ **Normalised**, allowing comparison across scenarios  
0 for non-contextuality ... 1 for strong contextuality
- ▶ Computable using **linear programming**
- ▶ Precise relationship to **violations of Bell inequalities**

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

- ▶ **General**, i.e. applicable to any measurement scenario
- ▶ **Normalised**, allowing comparison across scenarios  
0 for non-contextuality ... 1 for strong contextuality
- ▶ Computable using **linear programming**
- ▶ Precise relationship to **violations of Bell inequalities**
- ▶ **Monotone** wrt operations that don't introduce contextuality  
     $\rightsquigarrow$  **resource theory**

# Overview

We introduce the **contextual fraction**  
(generalising the notion of non-local fraction)

It satisfies a number of desirable properties:

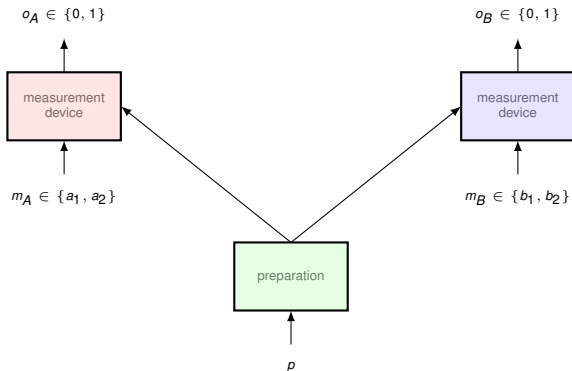
- ▶ **General**, i.e. applicable to any measurement scenario
- ▶ **Normalised**, allowing comparison across scenarios  
0 for non-contextuality ... 1 for strong contextuality
- ▶ Computable using **linear programming**
- ▶ Precise relationship to **violations of Bell inequalities**
- ▶ **Monotone** wrt operations that don't introduce contextuality  
     $\rightsquigarrow$  **resource theory**
- ▶ Relates to quantifiable **advantages** in QC and QIP tasks



# Contextuality

# Empirical data

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
$a_1$	$b_1$	$1/2$	0	0	$1/2$
$a_1$	$b_2$	$3/8$	$1/8$	$1/8$	$3/8$
$a_2$	$b_1$	$3/8$	$1/8$	$1/8$	$3/8$
$a_2$	$b_2$	$1/8$	$3/8$	$3/8$	$1/8$



# Abramsky–Brandenburger framework

Measurement scenario  $\langle X, \mathcal{M}, O \rangle$ :

- ▶  $X$  is a finite set of measurements or variables
- ▶  $O$  is a finite set of outcomes or values
- ▶  $\mathcal{M}$  is a cover of  $X$ , indicating **joint measurability** (contexts)

# Abramsky–Brandenburger framework

Measurement scenario  $\langle X, \mathcal{M}, O \rangle$ :

- ▶  $X$  is a finite set of measurements or variables
- ▶  $O$  is a finite set of outcomes or values
- ▶  $\mathcal{M}$  is a cover of  $X$ , indicating **joint measurability** (contexts)

**Example:** (2,2,2) Bell scenario

- ▶ The set of variables is  $X = \{a_1, a_2, b_1, b_2\}$ .
- ▶ The outcomes are  $O = \{0, 1\}$ .
- ▶ The measurement contexts are:

$$\{ \{a_1, b_1\}, \{a_1, b_2\}, \{a_2, b_1\}, \{a_2, b_2\} \}.$$

# Empirical Models

Joint outcome or **event** in a context  $C$  is  $s \in O^C$ , e.g.

$$s = [a_1 \mapsto 0, b_1 \mapsto 1] .$$

# Empirical Models

Joint outcome or **event** in a context  $C$  is  $s \in O^C$ , e.g.

$$s = [a_1 \mapsto 0, b_1 \mapsto 1] .$$

**Empirical model:** family  $\{e_C\}_{C \in \mathcal{M}}$  where  $e_C \in \text{Prob}(O^C)$  for  $C \in \mathcal{M}$ .

It specifies a probability distribution over the events in each context.

Each distribution is a row of the probability table.

# Empirical Models

Joint outcome or **event** in a context  $C$  is  $s \in O^C$ , e.g.

$$s = [a_1 \mapsto 0, b_1 \mapsto 1] .$$

**Empirical model:** family  $\{e_C\}_{C \in \mathcal{M}}$  where  $e_C \in \text{Prob}(O^C)$  for  $C \in \mathcal{M}$ .

It specifies a probability distribution over the events in each context.

Each distribution is a row of the probability table.

**Compatibility** condition: the distributions “agree on overlaps”

$$\forall C, C' \in \mathcal{M}. \quad e_C|_{C \cap C'} = e_{C'}|_{C \cap C'} .$$

# Empirical Models

Joint outcome or **event** in a context  $C$  is  $s \in O^C$ , e.g.

$$s = [a_1 \mapsto 0, b_1 \mapsto 1] .$$

**Empirical model:** family  $\{e_C\}_{C \in \mathcal{M}}$  where  $e_C \in \text{Prob}(O^C)$  for  $C \in \mathcal{M}$ .

It specifies a probability distribution over the events in each context.

Each distribution is a row of the probability table.

**Compatibility** condition: the distributions “agree on overlaps”

$$\forall C, C' \in \mathcal{M}. \quad e_C|_{C \cap C'} = e_{C'}|_{C \cap C'} .$$

In multipartite scenarios, compatibility = the **no-signalling** principle.



# Contextuality

A (compatible) empirical model is **non-contextual** if there exists a **global distribution**  $d \in \text{Prob}(O^X)$  on the joint assignments of outcomes to all measurements that marginalises to all the  $e_C$ :

$$\exists d \in \text{Prob}(O^X). \forall C \in \mathcal{M}. \quad d|_C = e_C .$$

# Contextuality

A (compatible) empirical model is **non-contextual** if there exists a **global distribution**  $d \in \text{Prob}(O^X)$  on the joint assignments of outcomes to all measurements that marginalises to all the  $e_C$ :

$$\exists d \in \text{Prob}(O^X). \forall C \in \mathcal{M}. \quad d|_C = e_C .$$

i.e. all the local information can be glued into a consistent global description.

# Contextuality

A (compatible) empirical model is **non-contextual** if there exists a **global distribution**  $d \in \text{Prob}(O^X)$  on the joint assignments of outcomes to all measurements that marginalises to all the  $e_C$ :

$$\exists d \in \text{Prob}(O^X). \forall C \in \mathcal{M}. \quad d|_C = e_C .$$

i.e. all the local information can be glued into a consistent global description.

## **Contextuality:**

family of data which is **locally consistent** but **globally inconsistent**.

# Contextuality

A (compatible) empirical model is **non-contextual** if there exists a **global distribution**  $d \in \text{Prob}(O^X)$  on the joint assignments of outcomes to all measurements that marginalises to all the  $e_C$ :

$$\exists d \in \text{Prob}(O^X). \forall C \in \mathcal{M}. \quad d|_C = e_C .$$

i.e. all the local information can be glued into a consistent global description.

## **Contextuality:**

family of data which is **locally consistent** but **globally inconsistent**.

The import of results such as Bell's and Bell–Kochen–Specker's theorems is that there are empirical models arising from quantum mechanics that are contextual.

# Strong contextuality

Strong Contextuality:

**no** event can be extended to a global assignment.

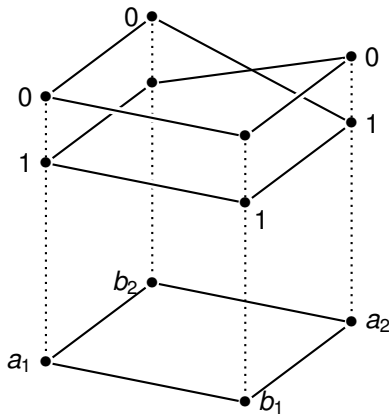
# Strong contextuality

Strong Contextuality:

**no** event can be extended to a global assignment.

E.g. K-S, GHZ, the PR box:

A	B	(0, 0)	(0, 1)	(1, 0)	(1, 1)
$a_1$	$b_1$	✓	×	×	✓
$a_1$	$b_2$	✓	×	×	✓
$a_2$	$b_1$	✓	×	×	✓
$a_2$	$b_2$	×	✓	✓	×



# The contextual fraction

# The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$



# The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

# The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions**  $c \in \text{SubProb}(O^X)$  such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

**Non-contextual fraction:** maximum weight of such a subdistribution.

## The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions**  $c \in \text{SubProb}(O^X)$  such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

**Non-contextual fraction:** maximum weight of such a subdistribution.

Equivalently, maximum weight  $\lambda$  over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e'$$

where  $e^{NC}$  is a non-contextual model.

## The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions**  $c \in \text{SubProb}(O^X)$  such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

**Non-contextual fraction:** maximum weight of such a subdistribution.

Equivalently, maximum weight  $\lambda$  over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e'$$

where  $e^{NC}$  is a non-contextual model.

# The contextual fraction

Non-contextuality: global distribution  $d \in \text{Prob}(O^X)$  such that:

$$\forall c \in \mathcal{M}. d|_c = e_c .$$

Which fraction of a model admits a non-contextual explanation?

Consider **subdistributions**  $c \in \text{SubProb}(O^X)$  such that:

$$\forall c \in \mathcal{M}. c|_c \leq e_c .$$

**Non-contextual fraction:** maximum weight of such a subdistribution.

Equivalently, maximum weight  $\lambda$  over all convex decompositions

$$e = \lambda e^{NC} + (1 - \lambda) e^{SC}$$

where  $e^{NC}$  is a non-contextual model.  $e^{SC}$  is strongly contextual!

$$\text{NCF}(e) = \lambda \qquad \text{CF}(e) = 1 - \lambda$$

# (Non-)contextual fraction via linear programming

Checking contextuality of  $e$  corresponds to solving

$$\begin{array}{ll}\text{Find} & \mathbf{d} \in \mathbb{R}^n \\ \text{such that} & \mathbf{M}\mathbf{d} = \mathbf{v}^e \\ \text{and} & \mathbf{d} \geq \mathbf{0} \quad .\end{array}$$

# (Non-)contextual fraction via linear programming

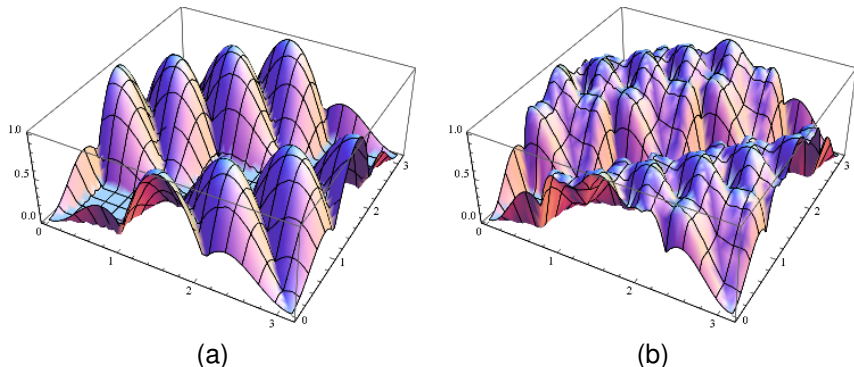
Checking contextuality of  $e$  corresponds to solving

$$\begin{array}{ll}\text{Find} & \mathbf{d} \in \mathbb{R}^n \\ \text{such that} & \mathbf{M}\mathbf{d} = \mathbf{v}^e \\ \text{and} & \mathbf{d} \geq \mathbf{0} \quad .\end{array}$$

Computing the non-contextual fraction corresponds to solving the following linear program:

$$\begin{array}{ll}\text{Find} & \mathbf{c} \in \mathbb{R}^n \\ \text{maximising} & \mathbf{1} \cdot \mathbf{c} \\ \text{subject to} & \mathbf{M}\mathbf{c} \leq \mathbf{v}^e \\ \text{and} & \mathbf{c} \geq \mathbf{0} \quad .\end{array}$$

## E.g. Equatorial measurements on GHZ( $n$ )



**Figure:** Contextual fraction of empirical models obtained with equatorial measurements at  $\phi_1$  and  $\phi_2$  on each qubit of  $|\psi_{\text{GHZ}(n)}\rangle$  with: (a)  $n = 3$ ; (b)  $n = 4$ .



# Violations of Bell inequalities

# Generalised Bell inequalities

An **inequality** for a scenario  $\langle X, \mathcal{M}, O \rangle$  is given by:

- ▶ a set of coefficients  $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound  $R$

# Generalised Bell inequalities

An **inequality** for a scenario  $\langle X, \mathcal{M}, O \rangle$  is given by:

- ▶ a set of coefficients  $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound  $R$

For a model  $e$ , the inequality reads as

$$\mathcal{B}_\alpha(e) \leq R ,$$

where

$$\mathcal{B}_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s) .$$

# Generalised Bell inequalities

An **inequality** for a scenario  $\langle X, \mathcal{M}, O \rangle$  is given by:

- ▶ a set of coefficients  $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound  $R$

For a model  $e$ , the inequality reads as

$$B_\alpha(e) \leq R,$$

where

$$B_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s).$$

Wlog we can take  $R$  non-negative (in fact, we can take  $R = 0$ ).

# Generalised Bell inequalities

An **inequality** for a scenario  $\langle X, \mathcal{M}, O \rangle$  is given by:

- ▶ a set of coefficients  $\alpha = \{\alpha(C, s)\}_{C \in \mathcal{M}, s \in O^C}$
- ▶ a bound  $R$

For a model  $e$ , the inequality reads as

$$B_\alpha(e) \leq R,$$

where

$$B_\alpha(e) := \sum_{C \in \mathcal{M}, s \in O^C} \alpha(C, s) e_C(s).$$

Wlog we can take  $R$  non-negative (in fact, we can take  $R = 0$ ).

It is called a **Bell inequality** if it is satisfied by every NC model. If it is saturated by some NC model, the Bell inequality is said to be **tight**.

# Violation of a Bell inequality

A Bell inequality establishes a bound for the value of  $\mathcal{B}_\alpha(e)$  amongst NC models.

# Violation of a Bell inequality

A Bell inequality establishes a bound for the value of  $\mathcal{B}_\alpha(e)$  amongst NC models.

For a general (no-signalling) model  $e$ , the quantity is limited only by

$$\|\alpha\| := \sum_{C \in \mathcal{M}} \max \left\{ \alpha(C, s) \mid s \in O^C \right\}$$

# Violation of a Bell inequality

A Bell inequality establishes a bound for the value of  $\mathcal{B}_\alpha(e)$  amongst NC models.

For a general (no-signalling) model  $e$ , the quantity is limited only by

$$\|\alpha\| := \sum_{C \in \mathcal{M}} \max \left\{ \alpha(C, s) \mid s \in O^C \right\}$$

The **normalised violation** of a Bell inequality  $\langle \alpha, R \rangle$  by an empirical model  $e$  is the value

$$\frac{\max\{0, \mathcal{B}_\alpha(e) - R\}}{\|\alpha\| - R}.$$



# Bell inequality violation and the contextual fraction

## Proposition

Let  $e$  be an empirical model.

# Bell inequality violation and the contextual fraction

## Proposition

Let  $e$  be an empirical model.

- ▶ The normalised violation by  $e$  of any Bell inequality is at most  $\text{CF}(e)$ .

# Bell inequality violation and the contextual fraction

## Proposition

Let  $e$  be an empirical model.

- ▶ The normalised violation by  $e$  of any Bell inequality is at most  $CF(e)$ .
- ▶ This bound is attained: there exists a Bell inequality whose normalised violation by  $e$  is exactly  $CF(e)$ .

# Bell inequality violation and the contextual fraction

## Proposition

Let  $e$  be an empirical model.

- ▶ The normalised violation by  $e$  of any Bell inequality is at most  $\text{CF}(e)$ .
- ▶ This bound is attained: there exists a Bell inequality whose normalised violation by  $e$  is exactly  $\text{CF}(e)$ .
- ▶ Moreover, this Bell inequality is tight at “the” non-contextual model  $e^{\text{NC}}$  and maximally violated by “the” strongly contextual model  $e^{\text{SC}}$  for any decomposition:

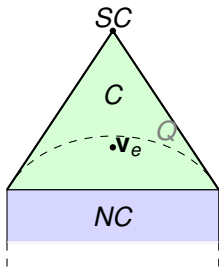
$$e = \text{NCF}(e)e^{\text{NC}} + \text{CF}(e)e^{\text{SC}}.$$

# Bell inequality violation and the contextual fraction

Quantifying Contextuality LP:

Find  $\mathbf{c} \in \mathbb{R}^n$   
maximising  $\mathbf{1} \cdot \mathbf{c}$   
subject to  $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$   
and  $\mathbf{c} \geq \mathbf{0}$  .

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$  with  $\lambda = \mathbf{1} \cdot \mathbf{x}^*$ .



# Bell inequality violation and the contextual fraction

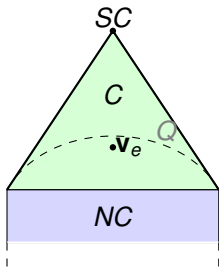
Quantifying Contextuality LP:

Find  $\mathbf{c} \in \mathbb{R}^n$   
maximising  $\mathbf{1} \cdot \mathbf{c}$   
subject to  $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$   
and  $\mathbf{c} \geq \mathbf{0}$  .

Dual LP:

Find  $\mathbf{y} \in \mathbb{R}^m$   
minimising  $\mathbf{y} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$   
and  $\mathbf{y} \geq \mathbf{0}$  .

$$e = \lambda e^{NC} + (1 - \lambda) e^{SC} \text{ with } \lambda = \mathbf{1} \cdot \mathbf{x}^*.$$



# Bell inequality violation and the contextual fraction

Quantifying Contextuality LP:

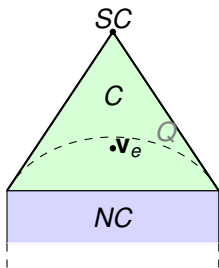
Find  $\mathbf{c} \in \mathbb{R}^n$   
maximising  $\mathbf{1} \cdot \mathbf{c}$   
subject to  $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$   
and  $\mathbf{c} \geq \mathbf{0}$  .

Dual LP:

Find  $\mathbf{y} \in \mathbb{R}^m$   
minimising  $\mathbf{y} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$   
and  $\mathbf{y} \geq \mathbf{0}$  .

$$\mathbf{e} = \lambda \mathbf{e}^{NC} + (1 - \lambda) \mathbf{e}^{SC} \text{ with } \lambda = \mathbf{1} \cdot \mathbf{x}^*.$$

$$\mathbf{a} := \mathbf{1} - |\mathcal{M}| \mathbf{y}$$

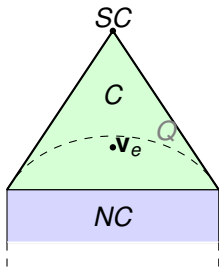


# Bell inequality violation and the contextual fraction

Quantifying Contextuality LP:

Find  $\mathbf{c} \in \mathbb{R}^n$   
maximising  $\mathbf{1} \cdot \mathbf{c}$   
subject to  $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$   
and  $\mathbf{c} \geq \mathbf{0}$  .

$e = \lambda e^{NC} + (1 - \lambda)e^{SC}$  with  $\lambda = \mathbf{1} \cdot \mathbf{x}^*$ .



Dual LP:

Find  $\mathbf{y} \in \mathbb{R}^m$   
minimising  $\mathbf{y} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$   
and  $\mathbf{y} \geq \mathbf{0}$  .

$$\mathbf{a} := \mathbf{1} - |\mathcal{M}| \mathbf{y}$$

Find  $\mathbf{a} \in \mathbb{R}^m$   
maximising  $\mathbf{a} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{a} \leq \mathbf{0}$   
and  $\mathbf{a} \leq \mathbf{1}$  .

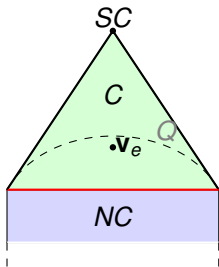


# Bell inequality violation and the contextual fraction

Quantifying Contextuality LP:

Find  $\mathbf{c} \in \mathbb{R}^n$   
maximising  $\mathbf{1} \cdot \mathbf{c}$   
subject to  $\mathbf{M}\mathbf{c} \leq \mathbf{v}^e$   
and  $\mathbf{c} \geq \mathbf{0}$  .

$$\mathbf{e} = \lambda \mathbf{e}^{NC} + (1 - \lambda) \mathbf{e}^{SC} \text{ with } \lambda = \mathbf{1} \cdot \mathbf{x}^*.$$



Dual LP:

Find  $\mathbf{y} \in \mathbb{R}^m$   
minimising  $\mathbf{y} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{y} \geq \mathbf{1}$   
and  $\mathbf{y} \geq \mathbf{0}$  .

$$\mathbf{a} := \mathbf{1} - |\mathcal{M}| \mathbf{y}$$

Find  $\mathbf{a} \in \mathbb{R}^m$   
maximising  $\mathbf{a} \cdot \mathbf{v}^e$   
subject to  $\mathbf{M}^T \mathbf{a} \leq \mathbf{0}$   
and  $\mathbf{a} \leq \mathbf{1}$  .

computes tight Bell inequality  
(separating hyperplane)

# Operations on empirical models

# Contextuality as a resource

# Contextuality as a resource

- ▶ More than one possible measure of contextuality.
- ▶ What properties should a good measure satisfy?

# Contextuality as a resource

- ▶ More than one possible measure of contextuality.
- ▶ What properties should a good measure satisfy?
- ▶ Monotonicity wrt operations that do not introduce contextuality
- ▶ Towards a resource theory  
as for entanglement (e.g. LOCC), non-locality, ...

# Operations and the contextual fraction

# Operations and the contextual fraction

Relabelling  $e[\alpha]$

# Operations and the contextual fraction

Relabelling  $e[\alpha]$

Restriction  $e \upharpoonright \mathcal{M}'$



# Operations and the contextual fraction

Relabelling  $e[\alpha]$

Restriction  $e \upharpoonright \mathcal{M}'$

Coarse-graining  $e/f$

# Operations and the contextual fraction

Relabelling  $e[\alpha]$

Restriction  $e \upharpoonright \mathcal{M}'$

Coarse-graining  $e/f$

Mixing  $\lambda e + (1 - \lambda)e'$

# Operations and the contextual fraction

Relabelling  $e[\alpha]$

Restriction  $e \upharpoonright \mathcal{M}'$

Coarse-graining  $e/f$

Mixing  $\lambda e + (1 - \lambda)e'$

Choice  $e \& e'$

# Operations and the contextual fraction

Relabelling  $e[\alpha]$

Restriction  $e \upharpoonright \mathcal{M}'$

Coarse-graining  $e/f$

Mixing  $\lambda e + (1 - \lambda)e'$

Choice  $e \& e'$

Tensor  $e_1 \otimes e_2$

# Operations and the contextual fraction

Relabelling  $\text{CF}(e[\alpha]) = \text{CF}(e)$

Restriction  $e \restriction \mathcal{M}'$

Coarse-graining  $e/f$

Mixing  $\lambda e + (1 - \lambda)e'$

Choice  $e \& e'$

Tensor  $e_1 \otimes e_2$

# Operations and the contextual fraction

Relabelling  $\text{CF}(e[\alpha]) = \text{CF}(e)$

Restriction  $\text{CF}(e \upharpoonright \mathcal{M}') \leq \text{CF}(e)$

Coarse-graining  $e/f$

Mixing  $\lambda e + (1 - \lambda)e'$

Choice  $e \& e'$

Tensor  $e_1 \otimes e_2$

# Operations and the contextual fraction

Relabelling  $CF(e[\alpha]) = CF(e)$

Restriction  $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining  $CF(e/f) \leq CF(e)$

Mixing  $\lambda e + (1 - \lambda)e'$

Choice  $e \& e'$

Tensor  $e_1 \otimes e_2$

# Operations and the contextual fraction

Relabelling  $CF(e[\alpha]) = CF(e)$

Restriction  $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining  $CF(e/f) \leq CF(e)$

Mixing  $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice  $e \& e'$

Tensor  $e_1 \otimes e_2$



# Operations and the contextual fraction

Relabelling  $CF(e[\alpha]) = CF(e)$

Restriction  $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining  $CF(e/f) \leq CF(e)$

Mixing  $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice  $CF(e \& e') = \max\{CF(e), CF(e')\}$

Tensor  $e_1 \otimes e_2$

# Operations and the contextual fraction

Relabelling  $CF(e[\alpha]) = CF(e)$

Restriction  $CF(e \upharpoonright \mathcal{M}') \leq CF(e)$

Coarse-graining  $CF(e/f) \leq CF(e)$

Mixing  $CF(\lambda e + (1 - \lambda)e') \leq \lambda CF(e) + (1 - \lambda)CF(e')$

Choice  $CF(e \& e') = \max\{CF(e), CF(e')\}$

Tensor  $CF(e_1 \otimes e_2) = CF(e_1) + CF(e_2) - CF(e_1)CF(e_2)$   
 $NCF(e_1 \otimes e_2) = NCF(e_1)NCF(e_2)$

# Contextual fraction and quantum advantages

# Contextual fraction and advantages

- ▶ Contextuality has been associated with quantum advantage in information-processing and computational tasks.

# Contextual fraction and advantages

- ▶ Contextuality has been associated with quantum advantage in information-processing and computational tasks.
- ▶ Measure of contextuality  $\rightsquigarrow$  quantify such advantages.

# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

- ▶ measurement-based quantum computing scheme  
( $m$  input bits,  $l$  output bits,  $n$  parties)

# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

- ▶ measurement-based quantum computing scheme  
( $m$  input bits,  $l$  output bits,  $n$  parties)
  - ▶ classical control:
    - ▶ pre-processes input
    - ▶ determines the flow of measurements
    - ▶ post-processes to produce the output
- only  $\mathbb{Z}_2$ -linear computations.



# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

- ▶ measurement-based quantum computing scheme ( $m$  input bits,  $l$  output bits,  $n$  parties)
  - ▶ classical control:
    - ▶ pre-processes input
    - ▶ determines the flow of measurements
    - ▶ post-processes to produce the output
- only  $\mathbb{Z}_2$ -linear computations.
- ▶ additional power to compute non-linear functions resides in certain resource empirical models.

# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

- ▶ measurement-based quantum computing scheme ( $m$  input bits,  $l$  output bits,  $n$  parties)
- ▶ classical control:
  - ▶ pre-processes input
  - ▶ determines the flow of measurements
  - ▶ post-processes to produce the output

only  $\mathbb{Z}_2$ -linear computations.

- ▶ additional power to compute non-linear functions resides in certain resource empirical models.
- ▶ Raussendorf (2013): If an  $\ell_2$ -MBQC **deterministically** computes a non-linear Boolean function  $f : 2^m \longrightarrow 2^l$  then the resource must be **strongly contextual**.

# Contextuality and MBQC

E.g. Raussendorf (2013)  $\ell_2$ -MBQC

- ▶ measurement-based quantum computing scheme ( $m$  input bits,  $l$  output bits,  $n$  parties)

- ▶ classical control:

- ▶ pre-processes input
- ▶ determines the flow of measurements
- ▶ post-processes to produce the output

only  $\mathbb{Z}_2$ -linear computations.

- ▶ additional power to compute non-linear functions resides in certain resource empirical models.

- ▶ Raussendorf (2013): If an  $\ell_2$ -MBQC **deterministically** computes a non-linear Boolean function  $f : 2^m \longrightarrow 2^l$  then the resource must be **strongly contextual**.

- ▶ Probabilistic version: non-linear function computed with sufficiently large probability of success implies contextuality.

# Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function  $f : 2^m \longrightarrow 2^l$  using  $\ell_2$ -MBQC

# Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function  $f : 2^m \longrightarrow 2^l$  using  $\ell_2$ -MBQC
- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between  $f$  and closest  $\mathbb{Z}_2$ -linear function)

where for Boolean functions  $f$  and  $g$ ,  $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$ .

# Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function  $f : 2^m \longrightarrow 2^l$  using  $\ell_2$ -MBQC
- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between  $f$  and closest  $\mathbb{Z}_2$ -linear function)

where for Boolean functions  $f$  and  $g$ ,  $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$ .

- ▶ **Average probability of success** computing  $f$  (over all  $2^m$  possible inputs):  $\bar{p}_S$ .

# Contextual fraction and MBQC

- ▶ **Goal:** Compute Boolean function  $f : 2^m \longrightarrow 2^l$  using  $\ell_2$ -MBQC
- ▶ **Hardness of the problem**

$$\nu(f) := \min \{d(f, g) \mid g \text{ is } \mathbb{Z}_2\text{-linear}\}$$

(average distance between  $f$  and closest  $\mathbb{Z}_2$ -linear function)

where for Boolean functions  $f$  and  $g$ ,  $d(f, g) := 2^{-m} |\{\mathbf{i} \in 2^m \mid f(\mathbf{i}) \neq g(\mathbf{i})\}|$ .

- ▶ **Average probability of success** computing  $f$  (over all  $2^m$  possible inputs):  $\bar{p}_S$ .
- ▶ Then,

$$1 - \bar{p}_S \geq \text{NCF}(e) \nu(f)$$

# Contextual fraction and cooperative games

- ▶ Game described by  $n$  formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.



# Contextual fraction and cooperative games

- ▶ Game described by  $n$  formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.
- ▶ If the formulae are  $k$ -consistent (at most  $k$  are jointly satisfiable), **hardness of the task** is  $\frac{n-k}{n}$ .  
(cf. Abramsky & Hardy, “Logical Bell inequalities”)

# Contextual fraction and cooperative games

- ▶ Game described by  $n$  formulae (one for each allowed input).
- ▶ These describe the winning condition that the corresponding outputs must satisfy.
- ▶ If the formulae are  $k$ -consistent (at most  $k$  are jointly satisfiable), **hardness of the task** is  $\frac{n-k}{n}$ .  
(cf. Abramsky & Hardy, “Logical Bell inequalities”)
- ▶ We have

$$1 - \bar{p}_S \geq \text{NCF} \frac{n-k}{n}$$

# Further directions

## Further directions

- ▶ **Negative Probabilities Measure**

## Further directions

- ▶ **Negative Probabilities Measure**

- ▶ Alternative relaxation of global probability distribution requirement.

# Further directions

- ▶ **Negative Probabilities Measure**

- ▶ Alternative relaxation of global probability distribution requirement.
- ▶ Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$

# Further directions

## ► Negative Probabilities Measure

- Alternative relaxation of global probability distribution requirement.
- Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$
- ... with minimal weight  $|q| = 1 + 2\epsilon$ .  
The value  $\epsilon$  provides alternative measure of contextuality.

# Further directions

## ► Negative Probabilities Measure

- Alternative relaxation of global probability distribution requirement.
- Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$
- ... with minimal weight  $|q| = 1 + 2\epsilon$ .  
The value  $\epsilon$  provides alternative measure of contextuality.
- How are these related?



# Further directions

## ► Negative Probabilities Measure

- Alternative relaxation of global probability distribution requirement.
- Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$
- ... with minimal weight  $|q| = 1 + 2\epsilon$ .  
The value  $\epsilon$  provides alternative measure of contextuality.
- How are these related?
- Corresponds to affine decomposition

$$e = (1 + \epsilon) e_1 - \epsilon e_2$$

with  $e_1$  and  $e_2$  both non-contextual.

# Further directions

## ► Negative Probabilities Measure

- Alternative relaxation of global probability distribution requirement.
- Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$
- ... with minimal weight  $|q| = 1 + 2\epsilon$ .  
The value  $\epsilon$  provides alternative measure of contextuality.
- How are these related?

- Corresponds to affine decomposition

$$e = (1 + \epsilon) e_1 - \epsilon e_2$$

with  $e_1$  and  $e_2$  both non-contextual.

- Corresponding inequalities  $|\mathcal{B}_\alpha(e)| \leq R$ .

# Further directions

## ► Negative Probabilities Measure

- Alternative relaxation of global probability distribution requirement.
- Find quasi-probability distribution  $q$  on  $O^X$  such that  $q|_C = e_C$
- ... with minimal weight  $|q| = 1 + 2\epsilon$ .  
The value  $\epsilon$  provides alternative measure of contextuality.
- How are these related?
- Corresponds to affine decomposition

$$e = (1 + \epsilon) e_1 - \epsilon e_2$$

with  $e_1$  and  $e_2$  both non-contextual.

- Corresponding inequalities  $|\mathcal{B}_\alpha(e)| \leq R$ .
- Cyclic measurement scenarios

# Further directions

- ▶ Negative Probabilities Measure
- ▶ **Signalling models**

# Further directions

- ▶ Negative Probabilities Measure
- ▶ **Signalling models**
  - ▶ Empirical data may sometimes not satisfy no-signalling (compatibility).

# Further directions

- ▶ Negative Probabilities Measure
- ▶ **Signalling models**
  - ▶ Empirical data may sometimes not satisfy no-signalling (compatibility).
  - ▶ Given a signalling table, can we quantify amount of no-signalling and contextuality?

# Further directions

- ▶ Negative Probabilities Measure
- ▶ **Signalling models**
  - ▶ Empirical data may sometimes not satisfy no-signalling (compatibility).
  - ▶ Given a signalling table, can we quantify amount of no-signalling and contextuality?
  - ▶ Connections with Contextuality-by-Default (Dzhafarov et al.)

# Further directions

- ▶ Negative Probabilities Measure
- ▶ Signalling models
- ▶ **Resource theory and algebra of empirical models**
  - ▶ Sequencing



# Further directions

- ▶ Negative Probabilities Measure
- ▶ Signalling models
- ▶ **Resource theory and algebra of empirical models**
  - ▶ Sequencing ( $\rightsquigarrow$  causality?)

# Further directions

- ▶ Negative Probabilities Measure
- ▶ Signalling models
- ▶ **Resource theory and algebra of empirical models**
  - ▶ Sequencing ( $\rightsquigarrow$  causality?)
  - ▶ Cf. “Noncontextual wirings”  
Amaral, Cabello, Terra Cunha, & Aolita (2017)

# Further directions

- ▶ Negative Probabilities Measure
- ▶ Signalling models
- ▶ **Resource theory and algebra of empirical models**
  - ▶ Sequencing ( $\rightsquigarrow$  causality?)
  - ▶ Cf. “Noncontextual wirings”  
Amaral, Cabello, Terra Cunha, & Aolita (2017)
  - ▶ What (else) is this resource useful for?

# Questions...



“The contextual fraction as a measure of contextuality”  
Samson Abramsky, RSB, & Shane Mansfield  
`arXiv:1705.07918[quant-ph]`