Causal contextuality and adaptive MBQC

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5th Workshop on Quantum Contextuality in Quantum Mechanics and Beyond (QCQMB 2022) Prague, 18th December 2022

Joint work with Cihan Okay













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► Related to talks by Samson & Amy, but only using a particular type of models.



• May have some relation to upcoming talk by Sivert.



Introduction



Quantum advantage

Contextuality / Nonclassicality

'Contextuality in measurement-based quantum computation', Raussendorf, PRA 2013.





MBQC: Classical control computer with access to quantum resources

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 ℓ_2 -MBQC: Classical control computer with access to quantum resources

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▶ Classical control restricted to \mathbb{Z}_2 -linear computation

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 $\ell_2\text{-}\mathsf{MBQC}:$ Classical control computer with access to quantum resources

- Classical control restricted to \mathbb{Z}_2 -linear computation
- Resource treated as a black box, described by its behaviour

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Theorem

If an ℓ_2 -MBQC deterministically computes a nonlinear Boolean function then the resource is strongly contextual.

The AND function

'Computational power of correlations', Anders & Browne, PRL 2009.





Adaptive MBQC



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- Why should the classical benchmark be so restrictive?
- ▶ We could think of a classical model that exploits this (causal) knowledge.

Can we find conditions on the computed functions that exclude even such classical HV models?

Non-locality

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Given $S \subset \Omega$, we write

$$\mathcal{Q}_{\mathcal{S}} \mathrel{\mathop:}= \prod_{\omega \in \mathcal{S}} \mathcal{Q}_{\omega} \qquad ext{and} \qquad \mathcal{A}_{\mathcal{S}} \mathrel{\mathop:}= \prod_{\omega \in \mathcal{S}} \mathcal{A}_{\omega}$$

If $S \subset T$ there are restriction maps

$$\mathcal{Q}_{S\subset T}: \mathcal{Q}_T \longrightarrow \mathcal{Q}_S$$
 and $\mathcal{A}_{S\subset T}: \mathcal{A}_T \longrightarrow \mathcal{A}_S$

A deterministic local model is given by a family of functions

$$f_\omega:\mathcal{Q}_\omega\longrightarrow\mathcal{A}_\omega\qquad (\omega\in\Omega).$$

E.g. bipartite scenario: $(\mathcal{Q}_A \longrightarrow \mathcal{A}_A) \times (\mathcal{Q}_B \longrightarrow \mathcal{A}_B)$.

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 $f:\mathcal{Q}_A\times\mathcal{Q}_B\longrightarrow\mathcal{A}_A\times\mathcal{A}_B \text{ such that } f(q_A,q_B)=(a_A,a_B)=(f_A(q_A),f_B(q_B)).$

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 $f: \mathcal{Q}_A \times \mathcal{Q}_B \longrightarrow \mathbf{D}(\mathcal{A}_A \times \mathcal{A}_B)$ such that $P_f(a_A \mid q_A, q_B) = P_f(a_A \mid q_A)$ and similarly for a_B .

Causal contextuality

'The sheaf-theoretic structure of definite causality', Gogioso & Pinzani, QPL 2021.



► A causal (partial) order between sites

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- A causal (partial) order between sites
- Classical models are allowed to use information from the causal past
- ▶ i.e. the answer at a given site may depend on the questions asked at sites in its past.
- Correspondingly, no-signalling gets relaxed, permitting signalling to the future.

NB: a special class of scenarios within the formalism presented by Samson & Amy.

- A Bell scenario consists of:
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A causal Bell scenario consists of:

- a **partially ordered** set Ω of **sites** or parties
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Notation: $\downarrow \omega := \{ \omega' \in \Omega \mid \omega' \le \omega \} \qquad \downarrow S := \bigcup_{\omega \in S} \downarrow \omega = \{ \omega' \in \Omega \mid \exists \omega \in S. \ \omega' \le \omega \}$

Deterministic classical causal models

A deterministic causally classical model is given by a family of functions

$$f_\omega: \mathcal{Q}_{\downarrow \omega} \longrightarrow \mathcal{A}_\omega \qquad (\omega \in \Omega).$$

E.g. bipartite scenario with $A \leq B$: $(\mathcal{Q}_A \longrightarrow \mathcal{A}_A) \times (\mathcal{Q}_A \times \mathcal{Q}_B \longrightarrow \mathcal{A}_B)$.

Equivalently, a function $f:\mathcal{Q}_\Omega\longrightarrow\mathcal{A}_\Omega$ such that for any $S\subset\Omega$,



 $f: \mathcal{Q}_A \times \mathcal{Q}_B \longrightarrow \mathcal{A}_A \times \mathcal{A}_B \text{ such that } f(q_A, q_B) = (a_A, a_B) = (f_A(q_A), f_B(q_A, q_B)).$

Adding probabilities. . .

 $\blacktriangleright \ f_{\omega}: \mathcal{Q}_{\downarrow \omega} \longrightarrow D(\mathcal{A}_{\omega}) \qquad (\omega \in \Omega)$

This yields the causal classical models.

E.g. bipartite scenario with $A \leq B$: $(\mathcal{Q}_A \longrightarrow D(\mathcal{A}_A)) \times (\mathcal{Q}_A \times \mathcal{Q}_B \longrightarrow D(\mathcal{A}_B))$.

▶ $f: \mathcal{Q}_{\Omega} \longrightarrow D(\mathcal{A}_{\Omega})$ such that for any $S \subset \Omega$,



This yields models that are no-signalling except from the past.

 $f: \mathcal{Q}_A \times \mathcal{Q}_B \longrightarrow D(\mathcal{A}_A \times \mathcal{A}_B)$ such that $P_f(a_A \mid q_A, q_B) = P_f(a_A \mid q_A)$ but not for a_B .

Measurement-based quantum computation

Adaptive $\ell_2\text{-}\mathsf{MBQC}$



- ▶ input size *m*
- output size /
- ▶ adaptive structure (Ω, \leq) with $n = |\Omega|$

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$$\succ T: \mathbb{Z}_2^n \longrightarrow \mathbb{Z}_2^n$$

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eq 0 \Rightarrow \omega \leq \omega'$

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 $\mathbf{q} = Q\mathbf{i} + T\mathbf{s}$ $\mathbf{s} \leftarrow e(\mathbf{q})$ $\mathbf{o} = Z\mathbf{s}$

implements a function $\mathbb{Z}_2^m \longrightarrow D(\mathbb{Z}_2^l)$.

Causal contextuality and adaptive MBQC

Main result

- Functions $g : \mathbb{Z}_2^m \longrightarrow \mathbb{Z}_2$ can be represented as *m*-variable polynomials in \mathbb{Z}_2 , $\pi(g)$.
- ▶ Functions $g : \mathbb{Z}_2^m \longrightarrow \mathbb{Z}_2^l$ are represented by *l*-tuples of *m*-variable polynomials $\pi(g) = \langle \pi(g)_1, \dots, \pi(g)_l \rangle.$

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Theorem

Let (e, Q, T, Z) be an Ω -adaptive ℓ_2 -MBQC protocol that **deterministically** computes a function $g : \mathbb{Z}_2^m \longrightarrow \mathbb{Z}_2^l$. If e is **causally classical** then each $\pi(g)_j$ is a polynomial with degree **at most the height of** Ω , where the height of a poset is the maximum length of a chain in it.

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NB: If Ω is flat, i.e. has heigh 1, one recovers Raussendorf's result about nonlinear functions.

Questions...

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